

## **Appendix B-2e**

### **Geophysical Prove-Out Documentation**

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# **Final Geophysical Prove-Out Work Plan**

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**Final  
Geophysical Prove-Out Work Plan**

**for**

**MEC Removal Action  
Bains Gap  
Fort McClellan, Alabama**

**Task Order 0004**

**Contract Number: W912DY-04-D-0011**

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Prepared For:  
**U.S. Army Engineering and Support Center  
Huntsville, Alabama**

Prepared By:  
**Tetra Tech EC INC.**

**November 2005**

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The views, opinions, and/or findings contained in this document are those of the author(s) and should not be construed as an official department of the Army position, policy, or decision, unless so designated by other documentation.

## TABLE OF CONTENTS

1.0	GPO Plan.....	1-1
1.1	Test Plot Design.....	1-1
1.1.1	Prove-out Size and Location.....	1-1
1.1.2	Seed Items.....	1-2
1.2	Site Preparation.....	1-3
1.3	Location Surveying.....	1-3
1.4	Background Geophysical Mapping.....	1-3
1.5	Quality Control.....	1-3
1.5.1	Equipment Warm-up.....	1-4
1.5.2	Record Sensor Position.....	1-4
1.5.3	Personnel Test.....	1-4
1.5.4	Vibration Test (Cable Shake).....	1-4
1.5.5	Static Background and Static Spike.....	1-5
1.5.6	Height Optimization.....	1-5
1.5.7	Six Line Test.....	1-5
1.5.8	Repeat Lines.....	1-7
1.6	Anomaly Avoidance.....	1-7
1.7	Seeding.....	1-7
1.8	Data Collection Variables.....	1-8
1.8.1	EM61 MK2.....	1-8
1.8.2	RTS.....	1-8
1.8.3	Constellation.....	1-8
1.8.4	Sensor Configurations.....	1-9
1.9	Data Analysis and Interpretation.....	1-10
1.10	Reacquisition.....	1-11
1.11	Data Evaluation.....	1-11
2.0	GPO Letter Report.....	2-1
2.1	Deliverables.....	2-1

## APPENDIX A - TABLES

Table A-1:	Geophysical Prove-Out Anomalies.....	A-1
Table A-2:	Corner Points.....	A-2

## APPENDIX B - FIGURES

Figure B-1:	Test Grid Location.....	B-1
Figure B-2:	Background Test.....	B-2

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**LIST OF ACRONYMS**

CEHNC	United States Army Engineering and Support Center, Huntsville
EM	Electromagnetic
Ft	Feet
DGPS	Differential Global Positioning System
DID	Data Item Description
GPO	Geophysical Prove-Out
Mv	Millivolts
OE	Ordnance and Explosives
PCMCIA	P.C. Memory Card International Association
PLS	Professional land surveyor
QA	Quality Assurance
QC	Quality Control
RTS	Robotic Total Station
TDEM	Time Domain Electromagnetic
UXO	Unexploded Ordnance

Final GPO Work Plan  
MEC Removal Action  
Bains Gap, Fort McClellan, Alabama

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CERTIFICATION

I certify under penalty of law that this document and all attachments were prepared under my direction or supervision according to a system designed to assure that qualified personnel properly gather and evaluate the information submitted. Based on my inquiry of the person or persons who manage the system, or those persons directly responsible for gathering the information, the information submitted is, to the best of my knowledge and belief, true, accurate, and complete. I am aware that there are significant penalties for submitting false information, including the possibility of fine and imprisonment for knowing violations.



Arthur B. Holcomb P.E.  
Program Manager



## **1.0 GPO PLAN**

The United States Army Engineering and Support Center Huntsville (CEHNC) has contracted Tetra Tech EC Inc. (TtEC), under Contract W912DY-04-D-0011, to perform a Geophysical Prove-Out (GPO) at Fort McClellan located in Anniston, Alabama. It is anticipated that the GPO task will be performed in November of 2005 in order to support the Bains Gap Removal Action (RA).

The objective of the GPO is to demonstrate and document the performance of the data acquisition methodology and spatial sampling protocols, sensor(s) and positioning equipment, data analysis and management systems, data transfer procedures, and the geophysical Quality Control (QC) and Quality Assurance (QA) system. The following components of the geophysical system will be evaluated during the GPO field program to ensure the program objectives will be met:

- Spatial sample density (i.e., line and station spacing)
- Navigation and positioning methodologies
- Sensor and positioning system platform (stability, noise characteristics and ergonomics)
- Data processing, analysis and interpretation, management and transfer system
- Quality Assurance (QA) Control, documentation protocol for data acquisition, processing and analysis and data management and transfer
- The personnel that are going to perform the production geophysical survey to ensure their ability to meet the data quality objectives.

### **1.1 TEST PLOT DESIGN**

TtEC constructed a test area at Fort McClellan in August of 2002. This test area has been modified several times, as it has served as a testing area for over three years. In addition to performing GPO's at the test area, TtEC has used the test area to perform quality control and assurance functions following changes in equipment, changes in field personnel, and operational procedures. The following document will refer to the construction of the existing GPO plot and summarize the actions to be performed during the upcoming GPO for the Bains Gap RA.

#### **1.1.1 Prove-out Size and Location**

The existing GPO area is located near the scrap yard off Bains Gap Road (Appendix B Figure B-1). The site is representative of the physical environment to be encountered during geophysical operations during the RA. The area contains two separate test areas; one area is "open" (Test Grid 1) and a dense, wooded area with foliage characterizes Test Grid 2. The wooded area

W912DY-04-D-0011, TO 0004  
November 2005

1-1



obstructions, trees, and foliage in Test Grid 2 are similar to those to be found in the area of concern near Bains Gap.



Test Grid 1 (center) and Test Grid 2 (right edge of photo) Fence near Test Grid 1

A fence is located approximately 30 feet from the northern side of the GPO test plot, as seen in the photo above. This will allow our geophysicist to determine if signal interference from this cultural feature adversely affects the geophysical sensors or positioning equipment.

#### 1.1.2 Seed Items

The seed items buried at the existing GPO are presented in Appendix A, Table A-1. The seed items are representative of the items that might be encountered during the Bains Gap project. There are fifty inert MEC items buried at depths that range from several inches to several feet (ft). The corner points of Test Grid 1 and Test Grid 2 are demarcated with rebar.



Representative GPO seed items

## **1.2 SITE PREPARATION**

## **1.3 LOCATION SURVEYING**

TtEC constructed Test Grids 1 and 2 near Bains Gap in August 2002 to meet the requirements of Data Item Description (DID) OE-005-05A.01. The existing GPO remains in accordance with DID Munitions Response (MR) 005-05A. The grid corners for each test grid were located using a high resolution Leica Robotic Total Station (RTS) survey instrument. The control points used for the RTS location survey were developed from pre-existing site monuments, which were established using a Differential Global Positioning System (DGPS) operated by a professional land surveyor (PLS). The PLS was used to determine and/or verify the position of all Test Grid corner points and seed items. Measurements of the seeded items were performed in accordance with DID MR-005-05A.

## **1.4 BACKGROUND GEOPHYSICAL MAPPING**

The background geophysical survey data for the existing GPO are presented in Appendix B, Figure B-2.

## **1.5 QUALITY CONTROL**

TtEC-specific instrument and functional checks will be performed at the beginning and end of every data acquisition session for the GPO survey. The TtEC test regimen includes the following:

- Acquisition personnel metal check (ensure no metal on acquisition personnel);
- Static position system check (accuracy and repeatability of position – 0.25 ft tolerance);
- Static “background” geophysical sensor check (repeatability of geophysical sensor measurements, influence of ambient noise –  $\pm 2.5$  mV tolerance, c2\_660 time gate (timegate 3));
- Static “spike” geophysical sensor check (repeatability of geophysical sensor measurements when metal object (i.e. trailer hitch ball) is present – within 20 % of standard response, c2\_660 time gate);
- Kinematic geophysical sensor check with test item (repeatability and comparability of measurements with sensor in motion) – aka TtEC “cloverleaf” or “rebar” test – align samples to 0.5 ft tolerance;
- Repeatability of overall data (re-survey of portion of the survey area during each data acquisition session - ensure background removal is within  $\pm 2$  mV, and repeatability of peak anomaly intensity within 20 % when position within 0.25 ft); and

- Occupation (kinematic) of known survey control (e.g., grid corners) during the acquisition session to ensure comparability, accuracy, and repeatability of the positioning systems (1 ft tolerance).

In addition to the above tests, an array of required tests will be performed at the commencement of the GPO program. The specific tests and their intervals are specified in DID MR-005-05. The tests include an equipment warm up, verification of sensor offset, personnel test, vibration (cable shake) test, static background and static spike test, height of sensor optimization, six line test, and collection of repeat data. As a quality control function, the GPO area will be used to validate significant changes in operational procedures, as well as changes in equipment, personnel or objectives. The test procedures outlined will be digitally documented and delivered to the client.

All field team members involved in data collection during the RA will be involved with data collection during the GPO to document their ability and efficiency to collect geophysical data as per the standards set forth in DID MR-005-05.

#### **1.5.1 Equipment Warm-up**

The geophysical sensor will be turned on and allowed to run for a minimum of five minutes prior to collecting data.

#### **1.5.2 Record Sensor Position**

The distance between the geophysical sensor and ground surface will be measured and recorded, as well as the offset between the positioning system detector and the geophysical sensor.

#### **1.5.3 Personnel Test**

Field team leaders will be accountable for and ensure that there is no metal (e.g., rings, chains, earrings, knives, wallets, belt buckles, et.) residing on personnel immediately prior to data acquisition activities.

#### **1.5.4 Vibration Test (Cable Shake)**

All cables will be shook in a manner simulating walking in rough terrain. Excessive noise induced from this test will be recorded and the appropriate corrective action(s) implemented (e.g., replace equipment cable, tighten connector, use tension relief device, etc.).



### 1.5.5 Static Background and Static Spike

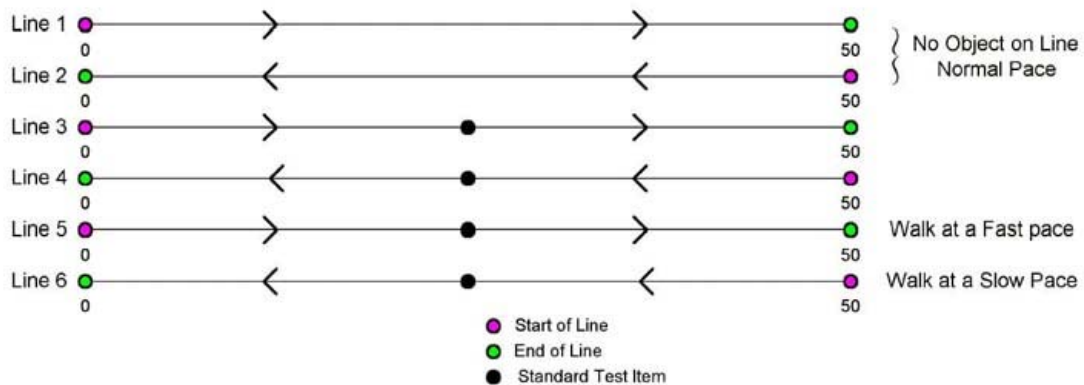
The static test involves locating the instrument over a “geophysically quiet” area and recording data for a minimum of three minutes, then placing a steel ball under the instrument and recording an additional three minutes of data.

### 1.5.6 Height Optimization

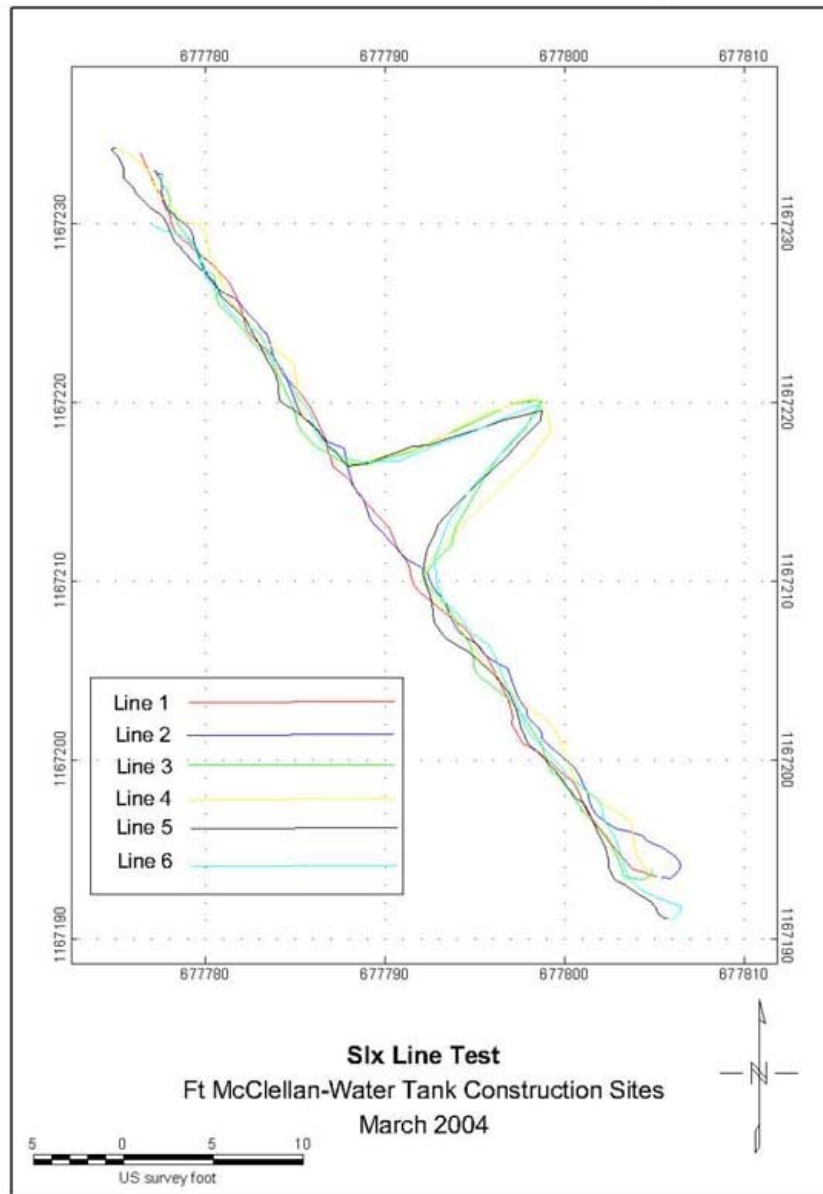
The data acquired at the GPO area will be used to ensure the sensor can reliably detect the smallest MEC item at the required depth. If necessary, the sensor distance above the ground will be decreased in order to meet this objective, while still maintaining an acceptable level of “noise” in the data.

### 1.5.7 Six Line Test

The six-line test involves collecting data along a one dimensional profile line six times. The purpose of the line test is to determine “noise” due to system movement/motion as well as potential location errors due to factors associated with system timing. For the first two line paths (1 and 2), data are collected along the line in opposite directions at a normal walking pace with no test item present. A steel ball (or equivalent) is then placed a known location on the path, and data collected along the line in equivalent manner to the first two lines (3 and 4). For the last two line paths, data are collected in one direction at a slow pace, and in the opposite direction at a faster pace (5 and 6). An example of the six-line test is presented in the following.



Final GPO Work Plan  
MEC Removal Action  
Bains Gap, Fort McClellan, Alabama



Six-line test data

W912DY-04-D-0011, TO 0004  
November 2005

1-6



#### **1.5.8 Repeat Lines**

At the end of each data acquisition session, the first line path will be repeated, or a diagonal path will be traversed across the grid that terminates at the start or end of the first line path.

#### **1.6 ANOMALY AVOIDANCE**

Anomaly avoidance techniques were used prior to placing wooden stakes and rebar at each corner and mid point of the test grids at the GPO area.

#### **1.7 SEEDING**

The inert MEC items presently located in Test Grid 1 at the GPO area are specified in Table A-1. These items were provided by CEHNC and were buried by TtEC personnel. All of the seeded items are inert MEC and painted blue and tagged with a non-biodegradable label identifying the item as inert and providing a reference of contact information. The following procedures were performed to seed Test Grid 1:

1. Inert items were labeled and photographed prior to burial.
2. Holes were dug with a shovel and/or a small backhoe.
3. The seed items were placed in the respective hole and the depth measured to the top of each item using a metal bar placed across the hole at ground level for reference. For larger seed items (e.g., 2.36 inch rocket) the depth was measured at the nose, tail and center point.
4. The location of the centroid of each item was then determined by using a high-resolution laser-based positioning system (Arc Second Constellation).



**Location survey of a seed item in the open hole (Constellation)**

5. The items were buried with one end of the metal bar on the item, and the dirt replaced in the hole. The metal bar was then removed..

## **1.8 DATA COLLECTION VARIABLES**

Based on our previous experience at numerous UXO sites including Ft. McClellan, the EM61 MK2 TDEM geophysical sensor exhibits the greatest potential to meet the project objectives. Based on the physical features present at the area of interest, laser-based positioning methods (RTS and Constellation) have the highest probability of providing accurate coordinate locations for the geophysical measurements.

### **1.8.1 EM61 MK2**

The Geonics Limited EM61 MK2 utilizes two coaxial receiver coils to measure the residual magnetic field generated by conductive and/or magnetic materials. The sensor electronics are designed to measure the residual magnetic field at a time when the response from conductive and/or magnetic objects is maximized, compared to the response from most earth materials. The use of two receiver coils also makes it possible to differentiate, in a simplistic fashion, shallow versus deep objects. An additional benefit of the specific design of the EM61 MK2 system is that it permits a more focused observation of the subsurface in areas of cultural interference, as well as in areas characterized by a high spatial density of subsurface metal objects. This is due to the mechanical design and operational parameters of the instrument, as well as the inherent nature of active electro-magnetic (EM) fields, which diminish in magnitude at a much higher rate than other sensor technologies such as magnetometry.

The EM61 MK2 utilizes multiple time-gates centered at 216, 366, 660, and 1,266  $\mu$ s. The signal intensity for a given ferrous target recorded by the earlier time-gates is generally a factor of 2 to 4 times that recorded by the standard EM61 MK1 time-gate. This feature facilitates a more reliable and repeatable interpretation of smaller targets such as 37mm projectiles.

### **1.8.2 RTS**

The Leica Geosystems 1105 or 1200 RTS is a laser-based positioning system that utilizes line-of-site to accurately determine the position of a 360-degree prism that is mounted at a known offset from the geophysical sensor. The RTS continuously records the position of the prism at a rate of approximately 3-4 Hz as it is transported across the area of interest. Coordinate and time of measurement data are stored on a PCMCIA device on the RTS, and uploaded to the processing computer a minimum of once per day.

### **1.8.3 Constellation**

The Arc Second Constellation is a laser-based positioning system that consists of four laser transmitters and a field computer for logging the position data via wireless modem. Four



Trimble Spectra Precision LS920 Laser Transmitters are positioned in a diamond or square geometry over 1/4 to 1 acre depending upon the density of obstacles present (e.g., trees). The transmitters are leveled, and an automatic routine calculates the relative x-y-z plane between the transmitters to a tolerance of one inch or less. A laser detector “wand” (i.e., receiver) is centered over the EMII MK2 coils on a TtEC-designed fiberglass “doghouse” (or equivalent). The detector wand receives the laser pulses from the four transmitters simultaneously, and computes a position based on the known position of the laser transmitters. Only two of the laser transmitters are necessary to compute a reliable position to a relative accuracy of approximately one inch. The position data are updated at 2-3 Hz and sent via wireless modem to the field computer for storage and display.

#### 1.8.4 Sensor Configurations

Due to the physical features present in the area of interest, the EM61 MK2 geophysical sensor will be integrated with the RTS and Constellation positioning systems. Based on our past site-specific experience at Fort McClellan, the RTS is the preferred positioning system in generally “open” areas, and the Constellation will provide positioning in the parcels at the site that are moderate to densely wooded. Based on past testing performed in the Bains Gap area by TtEC in 2001, DGPS is not the preferred positioning method (even in generally “open” areas) due to the presence of tall trees at the borders of the survey area, which degrade the GPS satellite signals.

The specific system configurations that will be tested at the existing GPO grid include the following:

**GPO Instrument Configurations**

Instrument	Coils	Time Gates	Positioning	Line Spacing (ft.)
EM61 MK2	1m by 1m	216 $\mu$ s, 366 $\mu$ s, 660 $\mu$ s	Constellation	~2.5
EM61 MK2	1m by 1m	216 $\mu$ s, 366 $\mu$ s, 660 $\mu$ s	RTS	~2.5

The physical features present at Test Grid 1 are representative of the “open” areas at the Bains Gap area of interest, and this area will be used to prove-out the EM61 MK2 and the RTS positioning system. A Juniper Allegro data recorder will be used to record the EM61 MK2 measurements at a rate of 12-15 Hz, and the RTS will be configured to record position measurements at a rate of approximately 3-4 Hz. The spacing between adjacent data acquisition transects will be ~2.5 ft.

The physical features present at Test Grid 2 (i.e., woods) will be used to validate the positioning accuracy of the Constellation system; a secondary objective at Test Grid 2 is to ensure that the data acquisition platform (i.e., integrated EM61 MK2 and Constellation system electronics) are

Final GPO Work Plan  
MEC Removal Action  
Bains Gap, Fort McClellan, Alabama

integrated to record measurements that can meet the project objectives. Placing several metal items on the ground surface at known locations, and collecting geophysical data over the entire area will validate the Constellation positioning system for project use. A Juniper Allegro data recorder will be used to record the EM61 MK2 measurements at a rate of 12-15 Hz, and the Constellation will be configured to record position measurements at a rate of approximately 3-4 Hz. The spacing between adjacent data acquisition transects will be ~ 2.5 ft.

The EM61 MK2 lower coil height will be adjusted so that it remains at a height of 16 inches (+/- 1 inch) above the ground surface. The height of the lower coil will be measured prior to each data acquisition session to ensure repeatability between different team members and different data acquisition sessions.

The man-portable (MP) "skirt" mode will be used during the GPO. In the TtEC man-portable configuration, two operators will be used to collect the geophysical data. One person transports the EM61 MK2 coils and positioning system detector while the other person, walking approximately ten ft behind, carries the EM61 MK2 electronics, Juniper Allegro data recorder, and the positioning system electronics (there are no electronics for the RTS configuration). The positioning system detector will be centered above the EM61 MK2 coils for both the RTS and Constellation system configurations.

## **1.9 DATA ANALYSIS AND INTERPRETATION**

Geophysical measurements and position data will be stored on digital media during data acquisition. After acquisition over the test grid is complete, data will be transferred to the site-processing center for initial data processing and evaluation. A TtEC geophysicist will perform preliminary geophysical and position data processing and QC checks in the field. The final analysis and interpretation of the data will be performed at a centralized processing center located at the TtEC Lakewood, Colorado or at the on-site TtEC field office. Processing, QC, analysis and interpretation of the data will be performed with internally developed software that has been specifically produced to integrate and assess digital geophysical data acquired with the RTS and Constellation positioning systems. These processed data are output to Geosoft Oasis Montaj Mapping software (version 6.2) to create color-coded images of sensor intensity for interpretation. All data channels of the EM61 MK2 will be analyzed to ensure the most comprehensive data interpretation.

In general, the post processing that will be performed includes removal of instrument bias, removal of timing errors (i.e., lag), and removal of geophysical sensor drift. Data will be recorded or transferred into the requested coordinate system (State plane zone Alabama North, NAD83). All data processing parameters are stored in digital files (\*.chk) or in the Oasis Montaj log file (\*.log).

Data will be interpreted at the processing center and a Microsoft Excel digsheet generated that is compatible with DID MR-005-05. This digsheet will be provided to the client project team for

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W912DY-04-D-0011, TO 0004  
November 2005

1-10



evaluation and scoring. The digsheet will also be provided to reacquisition personnel along with a color-coded image of sensor intensity for the target reacquisition phase of the GPO.

#### **1.10 REACQUISITION**

The TtEC reacquisition team will perform reacquisition of the interpreted geophysical anomalies using the digsheet. The RTS and Constellation positioning systems will be used by reacquisition personnel to validate both of these systems for project use. A hand held sensor (Vallon VMH3C, Minelab Explorer) or equivalent will be used by personnel to pinpoint the target specified on the digsheet, and these coordinates will be stored by the respective positioning system and/or recorded on the digsheet. The coordinates of the reacquired position will be compared to the interpreted coordinates on the digsheet to ensure the requirements in DID MR-005-005 are achieved; the requirement states that 95% of the reacquired locations shall fall within 1 meter of the target location as specified by the interpreter on the digsheet.

The Vallon and Minelab hand held TDEM systems use the same electronic technology as the EM61 MK2 system.

#### **1.11 DATA EVALUATION**

Data will be evaluated with respect to the number of seed items detected by each instrument configuration, production rate, and equipment reliability, functionality overall ease of use. The spatial sample density and “noise” level of each instrument configuration will be evaluated to ensure the data are of sufficient quantity and quality to meet the project objectives. Based on our past experience and the project objectives, the distance between adjacent acquisition tracks should not exceed 3.3 ft, and the kinematic “noise” level for the c2\_660 time gate (time gate 3) should be less than 4 mV (peak to peak) in “background” areas.



## **2.0 GPO LETTER REPORT**

### **2.1 DELIVERABLES**

The results of the GPO will be submitted in the GPO letter report in tabular and graphical form. The GPO Letter report will include, at a minimum, the following information:

- As-built drawing of the GPO plot;
- Pictures of the seed items;
- Color maps of the geophysical data;
- Summary of the GPO results;
- Proposed geophysical equipment, techniques, and methodologies; and
- Sufficient supporting information to justify the project team's recommendations, including manufacturer specifications for all recommended geophysical equipment, a definition of the expected target anomalies based upon the Archives Search Report, Site Inspection Report, Remedial Investigation/Feasibility Study or Engineering Evaluation/Cost Analysis results, or any other pertinent data/information used in decision making.

A CD shall be delivered with the letter report containing the following files:

- The GPO Letter Report (Microsoft Word format);
- All raw and processed geophysical data. All data, except raw instrument data, shall be provided in column delineated ASCII files in the format x, y, z, v1, v2, etc., where x and y are State Grid Plane Coordinates in Easting (meters) and Northing (meters) directions, z (elevation) is an optional field in meters, and v1, v2, v3, etc., are the instrument readings. The last data field will be a time stamp. Each data field will be separated by a comma or tab.
- Geophysical maps in their native format (Surfur®, Geosoft Oasis montaj™, Intergraph, or ESRI ArcView format) and/or as raster bit-map images such as BMP, JPEG, TIFF or GIF;
- Seed item location spreadsheet (Microsoft Excel format);
- Spreadsheet (Microsoft Excel format) of contractor picks for each sensor type, including reacquisition; and
- Spreadsheet (Microsoft Excel format) of all control points, survey points and benchmarks established or used during the Location Surveying task.

Final GPO Work Plan  
MEC Removal Action  
Bains Gap, Fort McClellan, Alabama

- The GPO Letter Report and Contracting Officer Approval Letter shall be included in geophysical reports and work plans associated with the survey area.

Final GPO Work Plan  
MEC Removal Action  
Bains Gap, Fort McClellan, Alabama

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**APPENDIX A  
TABLES**

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W912DY-04-D-0011, TO 0004  
November 2005



Final GPO Work Plan  
MEC Removal Action  
Bains Gap, Fort McClellan, Alabama

**TABLE A-1: GEOPHYSICAL PROVE-OUT SEED ITEMS - Test Grid 1**

X	Y	Target ID	Item	Depth(in)	Inclination
677699.94	1167164.58	a1	37mm	4.00	Horizontal
677708.37	1167173.14	a2	37mm	4.00	Vertical
677719.73	1167188.12	a3	81mm	34.00	Horizontal
677721.10	1167175.99	a4	2.36" rocket	26.00	Horizontal
677730.10	1167179.32	a5	rocket motor	12.00	Horizontal
677723.37	1167167.69	a6	37mm	16.00	Horizontal
677735.00	1167169.03	a7	60mm	12.00	Vertical
677735.62	1167156.66	a8	MKII HG	8.00	Vertical
677745.30	1167155.03	a9	2.36" rocket	6.00	Vertical
677743.41	1167136.92	a10	Anti Tank Mine	6.00	Horizontal
677726.67	1167132.67	a11	60mm	6.00	Vertical
677718.25	1167118.37	a12	MKII HG	4.00	Horizontal
677719.58	1167146.36	a13	37mm	0.00	Horizontal
677688.23	1167097.99	a14	3 "stokes	20.00	Horizontal
677704.27	1167108.58	a15	3 "stokes	32.00	Horizontal
677694.61	1167113.24	a16	75mm	30.00	Horizontal
677709.18	1167133.61	a17	60mm	25.00	45 degrees
677691.87	1167128.25	a18	75mm	12.00	Vertical
677681.35	1167118.85	a19	MKII HG	14.00	Horizontal
677673.49	1167132.86	a20	75mm	18.00	45 degrees
677666.45	1167141.88	a21	37mm	4.00	45 degrees
677680.90	1167152.03	a22	slap flare	4.00	45 degrees
677706.20	1167151.98	a23	105mm	45.00	45 degrees
677753.84	1167216.57	a24	37mm	4.00	Horizontal
677765.13	1167208.06	a25	37mm	4.00	Vertical
677771.70	1167196.19	a26	81mm	17.00	Horizontal
677771.95	1167190.79	a27	2.36" rocket	26.00	Horizontal
677781.41	1167187.60	a28	rocket motor	12.00	Horizontal
677794.28	1167178.14	a29	37mm	16.00	Horizontal
677775.16	1167162.11	a30	60mm	12.00	Vertical
677767.82	1167173.71	a31	MKII HG	8.00	Vertical
677763.33	1167167.94	a32	2.36" rocket	6.00	Vertical
677750.42	1167179.97	a33	60mm	6.00	Horizontal
677756.51	1167195.77	a34	60mm	6.00	Vertical
677740.94	1167197.48	a35	MKII HG	4.00	Horizontal
677741.04	1167180.67	a36	37mm	0.00	Horizontal
677728.58	1167178.52	a37	3 "stokes	20.00	Horizontal
677733.40	1167171.79	a38	3 "stokes	32.00	Horizontal
677743.27	1167161.79	a39	75mm	30.00	Horizontal
677758.76	1167148.27	a40	81mm	25.00	45 degrees
677697.46	1167163.21	a41	75mm	12.00	Vertical
677699.23	1167155.70	a42	MKII HG	0.00	Horizontal
677700.11	1167144.91	a43	75mm	18.00	45 degrees
677715.77	1167137.08	a44	37mm	4.00	45 degrees
677715.85	1167112.69	a45	slap flare	4.00	Vertical

W912DY-04-D-0011, T0004  
November 2005

A-1



Final GPO Work Plan  
MEC Removal Action  
Bains Gap, Fort McClellan, Alabama

<b>Table A-1: Geophysical Prove-Out Seed Items (Continued)</b>					
<b>X</b>	<b>Y</b>	<b>Target ID</b>	<b>Item</b>	<b>Depth (in)</b>	<b>Orientation</b>
677706.94	1167104.36	a46	105mm	10.00	Vertical
677693.62	1167134.69	a47	81mm	34.00	Vertical
677683.47	1167133.54	a48	rocket motor	12.00	Vertical
677680.56	1167145.54	a49	3 "stokes	20.00	Vertical
677674.37	1167119.69	a50	37mm	2.00	Horizontal

**TABLE A-2: GEOPHYSICAL PROVE-OUT CORNER POINTS and MIDPOINTS  
Test Grid 1 (ft)**

<b>Corner Point</b>	<b>X ft</b>	<b>Y ft</b>
SW	677693.96	1167088.76
SE	677796.54	1167176.86
NE	677753.19	1167226.71
NW	677651.45	1167138.05
M1	677762.26	1167147.30
M2	677728.18	1167117.92
M3	677685.25	1167167.49
M4	677719.52	1167196.53

**Test Grid 2 (ft)**

<b>Corner Point</b>	<b>X ft</b>	<b>Y ft</b>
SW	677825.1	1167325.0
SE	677868.1	1167300.0
NE	677911.9	1167375.0
NW	677869.0	1167401.0

TtEC proposes placing four inert 37mm projectiles (or larger) items on the surface at the following locations in Test Grid 2:

<b>Item</b>	<b>X ft</b>	<b>Y ft</b>
37mm	677846.0	1167337.0
37mm	677877.0	1167362.0
37mm	677885.0	1167330.0
37mm	677871.0	1167393.0



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MEC Removal Action  
Bains Gap, Fort McClellan, Alabama

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**APPENDIX B  
FIGURES**

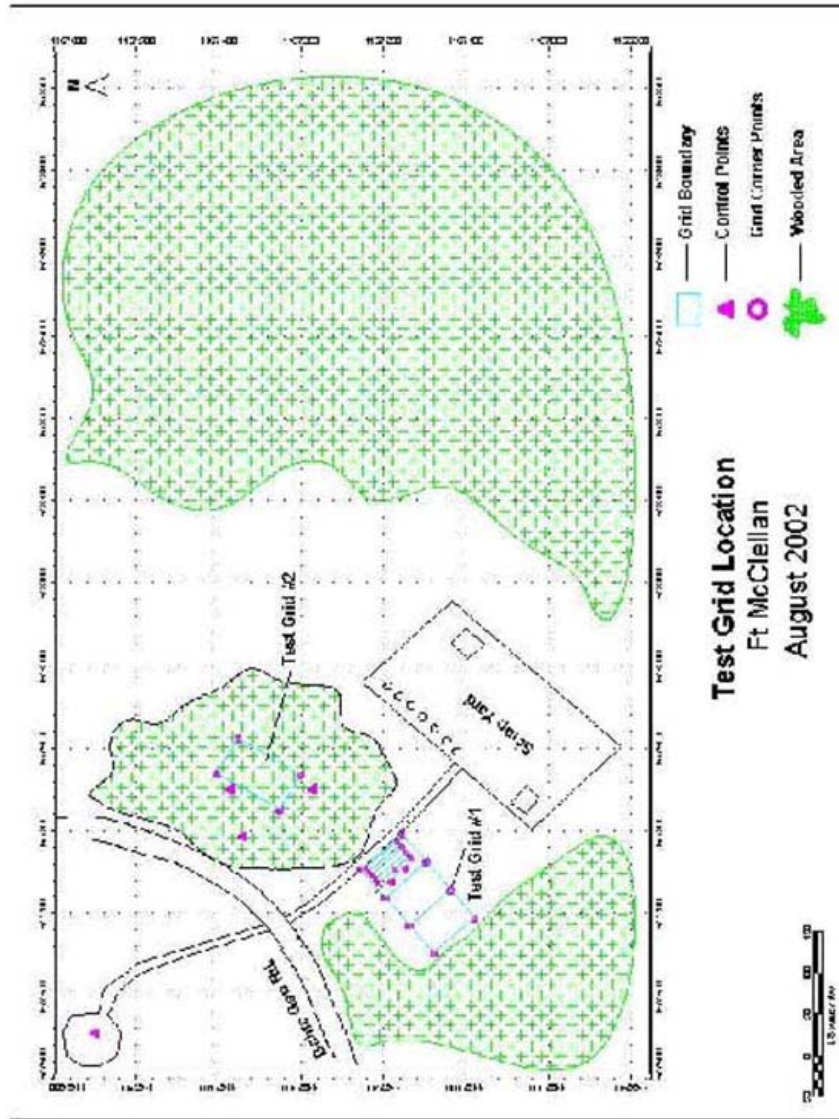
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W912DY-04-D-0011, TO 0004  
November 2005



Final GPO Work Plan  
 MEC Removal Action  
 Bains Gap, Fort McClellan, Alabama

FIGURE B-1: TEST GRID LOCATION

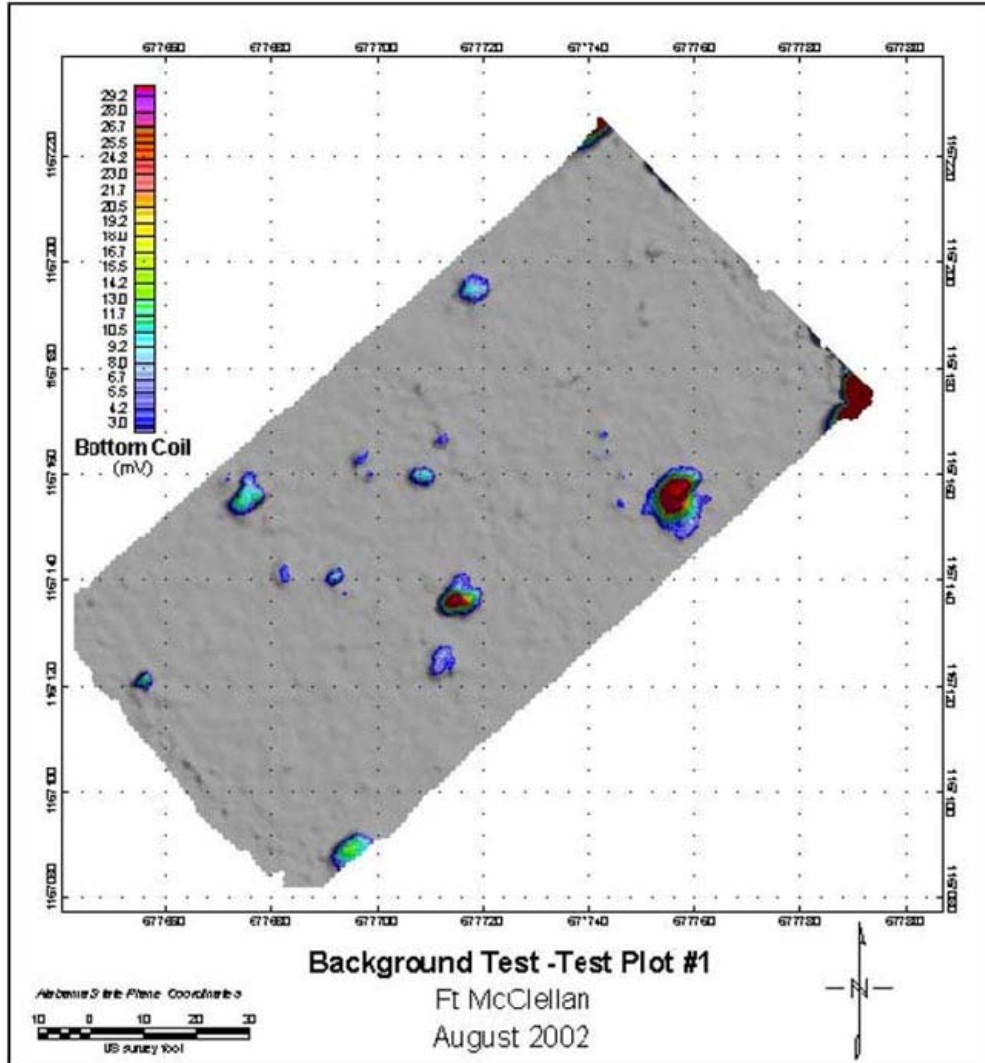


W912DY-04-D-0011, TO 0004  
 November 2005



Final GPO Work Plan  
MEC Removal Action  
Bains Gap, Fort McClellan, Alabama

FIGURE B-2: BACKGROUND TEST (Test Grid 1)



W912DY-04-D-0011, TO 0004  
November 2005

B-2



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**Final  
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**for**

**MEC Removal Action  
Bains Gap  
Fort McClellan, Alabama**

**Task Order 0004**

**Contract Number: W912DY-04-D-0011**

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Prepared For:  
**U.S. Army Engineering and Support Center  
Huntsville, Alabama**

Prepared By:  
**Tetra Tech EC INC.**

**March 2006**

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The views, opinions, and/or findings contained in this document are those of the author(s) and should not be construed as an official department of the Army position, policy, or decision, unless so designated by other documentation.

Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama

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### **CERTIFICATION**

I certify under penalty of law that this document and all attachments were prepared under my direction or supervision according to a system designed to assure that qualified personnel properly gather and evaluate the information submitted. Based on my inquiry of the person or persons who manage the system, or those persons directly responsible for gathering the information, the information submitted is, to the best of my knowledge and belief, true, accurate, and complete. I am aware that there are significant penalties for submitting false information, including the possibility of fine and imprisonment for knowing violations.



Arthur B. Holcomb P.E.

Program Manager



## TABLE OF CONTENTS

<b>1.0</b>	<b>INTRODUCTION.....</b>	<b>1</b>
<b>2.0</b>	<b>OBJECTIVE .....</b>	<b>1</b>
<b>3.0</b>	<b>LOCATION .....</b>	<b>1</b>
<b>4.0</b>	<b>EQUIPMENT .....</b>	<b>2</b>
4.1	EM61 MK2 .....	2
4.2	Constellation .....	2
4.3	Robotic Total Station .....	3
4.4	Seed Items .....	3
<b>5.0</b>	<b>PROCEDURES .....</b>	<b>3</b>
5.1	Data Acquisition.....	3
5.2	Data Processing .....	3
5.3	Data Interpretation .....	4
5.4	Reacquisition.....	4
5.5	Quality Control.....	4
5.6	Static Tests .....	4
5.7	Six-Line Tests .....	5
5.8	Positioning Tests .....	5
5.9	Personnel and Shake Tests .....	5
5.10	Results .....	5
<b>6.0</b>	<b>CONCLUSIONS AND RECOMMENDATIONS.....</b>	<b>6</b>
6.1	Conclusions and Recommendations.....	6

## LIST OF APPENDICIES

Appendix A	Test Grid Location
Appendix B	Background Test Grid
Appendix C	Tables
Appendix D	Static Test
Appendix E	Six Line Test
Appendix F	Test Grid As-Built Drawings
Appendix G	RTS and Constellation Tests

## **1.0 INTRODUCTION**

The United States Army Engineering and Support Center, Huntsville (USAESCH) has contracted Tetra Tech EC Inc. (TtEC) under Contract W912DY-04-D-0011, to perform a Geophysical Prove-Out (GPO) at Fort McClellan located in Anniston, Alabama. The GPO was performed on February 1<sup>st</sup>, 2006 to demonstrate the geophysical equipment and procedures to be used for the geophysical survey during the Bains Gap Removal Action (RA). The Geophysical Prove-Out Work Plan provides the details of the approach, methods and operational procedures used at the GPO.

## **2.0 OBJECTIVE**

The objective of the GPO is to demonstrate and document the performance of the data acquisition methodology and spatial sampling protocols, sensor(s) and positioning equipment, data analysis and management systems, data transfer procedures, and the geophysical Quality Control (QC) and Quality Assurance (QA) system. The following components of the geophysical system were evaluated during the GPO field program to ensure the program objectives will be met:

- Spatial sample density (i.e., line and station spacing)
- Navigation and positioning methodologies
- Sensor and positioning system platform (stability, noise characteristics and ergonomics)
- Data processing, analysis and interpretation, management and transfer system
- Quality Assurance (QA) Control, documentation protocol for data acquisition, processing and analysis and data management and transfer
- The personnel that are going to perform the production geophysical survey also perform the GPO to ensure their ability to meet the data quality objectives.

## **3.0 LOCATION**

The GPO area is located near the scrap yard off of Bains Gap Road (see Appendix A). The GPO area is representative of the environment encountered during geophysical operations at Fort McClellan including wooded areas, tree lines, roads, high brush, cultural features and open areas. The area contains two separate test areas; one area is "open" (Test Grid 1) and a dense, wooded area with foliage characterizes Test Grid 2. The wooded area obstructions, trees, and foliage in Test Grid 2 are similar to those to be found in the area of concern near Bains Gap.

## **4.0 EQUIPMENT**

Based on our previous experience at numerous UXO sites including Ft. McClellan, the EM61 MK2 TDEM geophysical sensor exhibits the greatest potential to meet the project objectives. Based on the physical features present at the area of interest, laser-based positioning methods (RTS and Constellation) have the highest probability of providing accurate coordinate locations for the geophysical measurements.

### **4.1 EM61 MK2**

The Geonics Limited EM61 MK2 is a high sensitivity high resolution time-domain metal detector which is used to detect both ferrous and non-ferrous metallic objects. It consists of a powerful transmitter that generates a pulsed primary magnetic field, which induces eddy currents in nearby metallic objects. The decay of these currents is measured by two receiver coils mounted on the coil assembly. The EM61 MK2 utilizes two coaxial receiver coils to measure the residual magnetic field generated by conductive and/or magnetic materials. The sensor electronics are designed to measure the residual magnetic field at a time when the response from conductive and/or magnetic objects is maximized, compared to the response from most earth materials. The use of two receiver coils also makes it possible to differentiate, in a simplistic fashion, shallow versus deep objects. An additional benefit of the specific design of the EM61 MK2 system is that it permits a more focused observation of the subsurface in areas of cultural interference, as well as in areas characterized by a high spatial density of subsurface metal objects. This is due to the mechanical design and operational parameters of the instrument, as well as the inherent nature of active electro-magnetic (EM) fields, which diminish in magnitude at a much higher rate than other sensor technologies such as magnetometry.

The EM61 MK2 utilizes multiple time-gates centered at 216, 366, 660, and 1,266  $\mu$ s. The signal intensity for a given ferrous target recorded by the earlier time-gates is generally a factor of 2 to 4 times that recorded by the standard EM61 MK1 time-gate. This feature facilitates a more reliable and repeatable interpretation of smaller targets such as 37mm projectiles.

### **4.2 CONSTELLATION**

The Arc Second Constellation is the positioning system that will be utilized in the medium to heavily wooded areas. The Arc Second Constellation is a laser-based positioning system that consists of four laser transmitters and a field computer for logging the position data via wireless modem. Four Trimble Spectra Precision LS920 Laser Transmitters are positioned in a diamond or square geometry over 1/4 to 1 acre depending upon the density of obstacles present (e.g., trees). The transmitters are leveled, and an automatic routine calculates the relative x-y-z plane between the transmitters to a tolerance of one inch or less. A laser detector "wand" (i.e., receiver) is centered over the EM61 MK2 coils on a TtEC-designed fiberglass "doghouse" (or equivalent). The detector wand receives the laser pulses from the four transmitters simultaneously, and computes a position based on the known position of the laser transmitters. Only two of the laser transmitters are necessary to compute a reliable position to a relative accuracy of approximately one inch. The position data are updated at 2-3 Hz and sent via wireless modem to the field computer for storage and display.



#### **4.3 ROBOTIC TOTAL STATION**

The RTS will be utilized as the positioning method, as needed, in areas that are open, or lightly wooded. The Leica Geosystems 1105 RTS is a laser-based positioning system that utilizes line-of-sight to accurately determine the position of a 360-degree prism that is mounted at a known offset from the geophysical sensor. The RTS continuously records the position of the prism at a rate of approximately 3-4 Hz as it is transported across the area of interest. Coordinate and time of measurement data are stored on a PCMCIA device on the RTS, and uploaded to the processing computer a minimum of once per day.

#### **4.4 SEED ITEMS**

The seed items buried at the existing GPO are presented in Appendix C, Table 1. The seed items are representative of the items that might be encountered during the Bains Gap project. There are fifty inert MEC items buried at depths that range from several inches to several feet (ft). Photographs of the seeded items will be submitted on a CD-ROM. For the wooded test grid, hand-held instruments were used to remove any subsurface metal. A background survey of the wooded test grid was subsequently performed and is presented in Appendix B. The wooded test grid was seeded with 11 scrap metal items on the surface to ascertain the positional accuracy of the Constellation system. The as-built drawings for the test grids can be found in Appendix F.

#### **5.0 PROCEDURES**

##### **5.1 DATA ACQUISITION**

The open test grid was surveyed twice during the GPO, once using the RTS and once using the Constellation. The wooded test grid was surveyed using the Constellation. For each of the surveys, data was acquired at a line spacing of 2.5 ft and at a sample rate of 12-15 times per second. The along line sampling is between 3.0 and 4.0 samples/ft depending on the operator's speed, which can vary slightly based on terrain. Prior to starting the acquisition session, the coil height was measured to 16 inches above ground level. Shake tests were performed to verify that all cables were secure in position. All four channels were electronically nulled to zero in a magnetically "quiet" area using the Geonics MKII acquisition software. Following these procedures, static and dynamic data were recorded to facilitate shift and drift corrections. The operators who will be acquiring data in the field collected the data in the GPO.

##### **5.2 DATA PROCESSING**

Data were stored on PCMCIA cards or a laptop computer during data acquisition. After data acquisition was completed at each test grid, data was transferred to the site laptop PC for processing. A TtEC geophysicist performed preliminary geophysical and navigation data processing and Quality Control (QC) checks. The final analysis and interpretation of the data was performed at the TtEC processing center at Ft. McClellan, Alabama. Processing was performed with internally developed software that has been specifically produced to integrate and interpret digital geophysical data acquired with the RTS and Constellation Positioning Systems. Geosoft Oasis Montaj Mapping software was also used to graphically display data and select targets. Data transfer was fully tested during the GPO. This included the transfer of raw

EM and positioning data. Corrected and leveled processed data were converted to space delimited ASCII format and delivered to USACE.

### **5.3 DATA INTERPRETATION**

All anomalies detected during each of the test grid surveys were selected as potential targets for intrusive investigation. The horizontal 37mm at 16 inches will be the smallest signature item to use for a lower threshold for "digs". The 37mm had a response of 8.3 mV on the 216us time gate and 5.4 mV on the 366 us time gate, and is visible on 2 adjacent acquisition lines. Although it is not anticipated to encounter a 37mm at 16 inches, TtEC will be conservative in the selection process. It is anticipated that the minimum dig selection criteria will be a 3 to 5 mV response on the 366 us time gate and/or 6 to 8 mV on the 216 us time gate, visible on 2 adjacent lines, and a response higher on the upper coil than the lower coil (660 us time gate), if the noise levels permit.

### **5.4 REACQUISITION**

The RTS was used for target reacquisition. Because 92% of the interpreted anomaly locations in the open GPO are within the DID 35cm requirement, and 100% of the interpreted locations are within the DID requirement in the wooded GPO, it is recommended that a hand held instrument not be used during reacquisition and the dig teams dig the interpreted anomaly flag location. This will prevent the reacquisition team from inadvertently mis-positioning the intended anomaly location. The intrusive teams are to record the offset from flagged locations and actual locations. TtEC will utilize the feedback process in a timely fashion to ensure that we are in fact intrusively investigating the interpreted geophysical anomalies, and should discrepancies start to occur, reacquisition will be one of the factors re-evaluated (as well as geology, EM navigation, positioning, etc).

### **5.5 QUALITY CONTROL**

Instrument and functionality checks were performed at the beginning and end of every data acquisition session during the GPO. Independent QC tests performed included personnel and shake tests, static test, 6-line test, and positioning test.

### **5.6 STATIC TESTS**

The static test involved locating the instrument over a quiet area and recording data for 5 minutes, then placing a spherical item under the instrument and recording an additional 5 minutes of data. Each of the instrument configuration static tests showed normal background noise levels (0 to 2 mV for the bottom coil and 0 to 4 mV for the upper coil. Slight variations were due to normal instrument noise and the operator reacting to the many insects swarming around which caused slight movement due to slapping motions. The operator moving caused noise below the inherent system noise (movement noise in the order of 0.1-0.15 mV) therefore would not effect field operations. The figures located in Appendix D represent the static calibration and static response. The purpose is to inspect the consistency of the instrument response throughout the course of the project.



## **5.7 SIX-LINE TESTS**

The six-line test (see Appendix E) involved collecting data along a 60-foot line six times. The purpose of this line test was to determine noise due to system movement/motion as well as location error caused by temporal time lag or spatial correction due to waypoint placement. For the first two line tests, data was collected along the line in each direction (Lines 1 and 2) at a normal pace with no item present. Lines 3 and 4 were collected (with the item in place) at a normal pace, followed by lines 5 and 6 collected at a fast pace and a slow pace, respectively. There was no appreciable noise increase from the tests nor was there appreciable position lag errors with the exception of the fast line on the open test grid. The coil operator walked so fast that the RTS was unable to keep up and did not record any positions along this line. This is not a concern, as the data acquisition team will not be collecting data at this fast speed. The test was performed along the east side of the test grid.

## **5.8 POSITIONING TESTS**

To test the positioning, the EM61 MK2 and navigation unit recorded data over the northeast corner of the test grid. After data processing, the geophysical position data was compared to the survey data to ensure that the positions were the same.

## **5.9 PERSONNEL AND SHAKE TESTS**

The coil operator was checked for metallic objects that may interfere with the EM signal. The cables were then shaken and the allegro monitored for noise. The coil operator also did some moving around while the data was monitored. No noise was detected during these tests.

## **5.10 RESULTS**

In the open test grid using the RTS, the data collection procedures are very good. The data navigation (line spacing) is excellent (no data gaps), and the positioning is very accurate as well. All 4 of the EM61 MK2 data channels have very low noise (<1.0mV). All of the interpreted anomaly locations were within 1 meter of the actual seed item location (100%), and 46 of 50 (92%) interpreted anomaly locations were within 35cm of the actual locations. The 4 seed items outside of 35cm are two 2.36" rockets at 26" depth, a 60mm at 25" depth, and a 37 mm next to a 75mm (2.75 feet away). A color-coded map of the geophysical data for the open test grid (366 us time-gate) is presented in Appendix G.

In the wooded test grid using the Constellation, the data collection procedures and equipment are also very good. The navigation (line spacing) is very good and the only data gaps are due to trees. The positioning is sufficient to meet the project objectives. The constellation timing issues appear to be affecting the positioning of the EM data. At its worst, the positioning errors are ~ 1.0 to 1.5 feet. This timing issue is inherent with this system and there is not much that can be done to correct these errors. The data processor and data interpreter will need to be aware of it during interpretation and account for it where possible. All of the seed items were interpreted and reacquired to within 35 cm of their actual location. The noise levels on the bottom coil are very low, although the top coil has more noise than what was seen in the open grid using the RTS. Because the "wand" cable was attached for all of the GPO test grids (RTS and Constellation) it appears that the noise is not due to the cable itself, but the signal coming

Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama

through the cable when the wand is active. The noise is not significant, (3 to 4 mV when present) but some testing will be performed to see if it can be reduced (e.g., move the cable away from the coil). A color-coded map of the geophysical data for the wooded test grid (366 us time-gate) is presented in Appendix G.

The results of the open test grid utilizing the Constellation were very similar to the results of the open test grid utilizing the RTS. All of the seed items were detected with the same degree of accuracy. A color-coded map of the geophysical data for the open test grid (366 us time-gate) utilizing the Constellation positioning is presented in Appendix G.

## **6.0 CONCLUSIONS AND RECOMMENDATIONS**

### **6.1 CONCLUSIONS AND RECOMMENDATIONS**

The GPO test grids at Fort McClellan are a very good indication of the types of areas that will be surveyed during the removal action. It is anticipated that trees, cultural features and open areas will all be encountered during the geophysical survey. The items seeded in the prove-out are also representative of the items to be encountered during the investigation.

The GPO was conducted to demonstrate and document the performance of the proposed data acquisition methodology (including personnel) and spatial sampling protocols, sensor(s) and positioning equipment, data analysis and management systems, data transfer procedures, and the geophysical Quality Control (QC) system.

Based on the results of the GPO, the EM61 MK2, coupled with either the RTS in the open areas, or the Constellation in the wooded areas, and utilizing the procedures described in the GPO Work Plan, demonstrated the ability to meet the program objectives. Because the interpretation position accuracy is very good, TtEC will not utilize a handheld sensor during target reacquisition and will instead dig the interpreted location. TtEC will need to continually utilize the feedback process to ensure anomaly recovery.

Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama

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**APPENDIX A  
TEST GRID LOCATION**

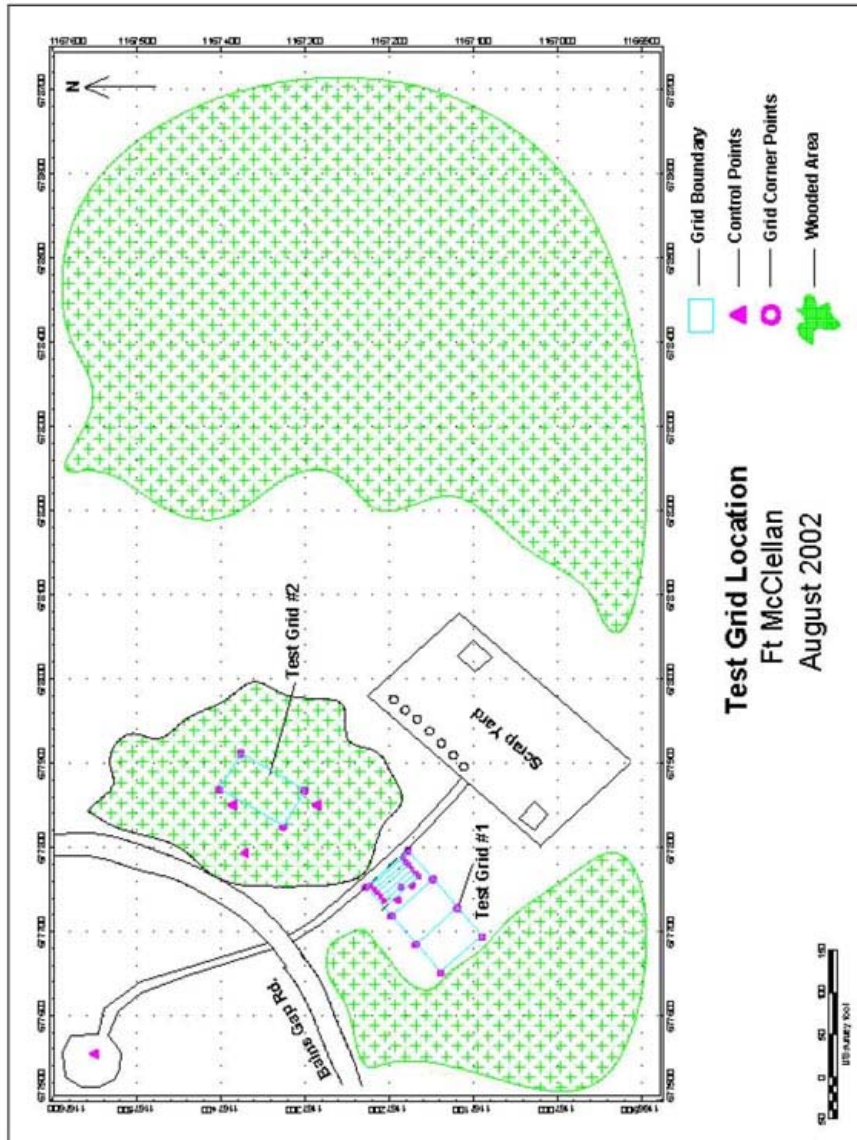
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Contract W912DY-04-D-0011, TO 004  
March 2006





Final Geophysical Prove-Out Letter Report  
 MEC Removal Action, Bains Gap  
 Fort McClellan, Alabama



Contract W912DY-04-D-0011, TO 004  
 March 2006

A-1

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Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama

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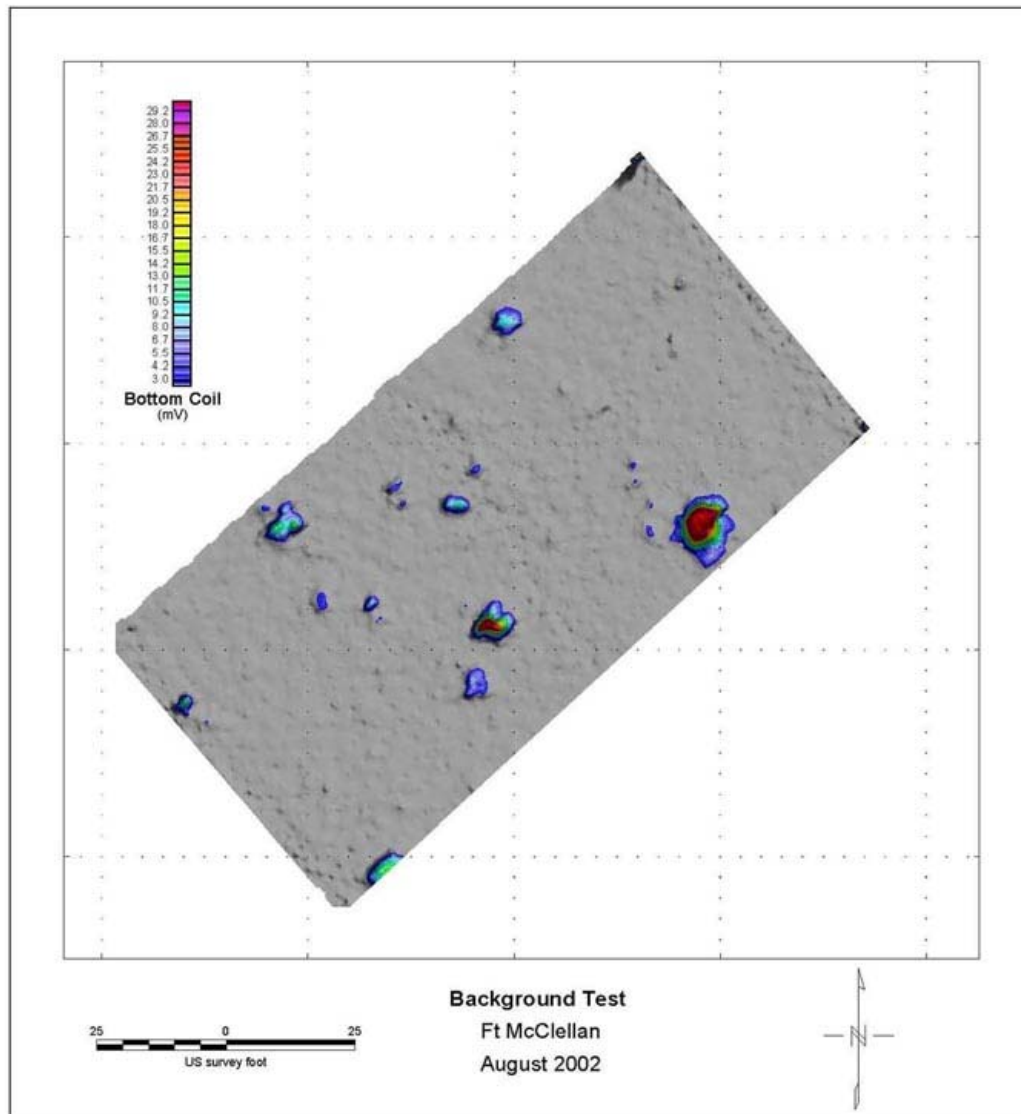
**APPENDIX B  
BACKGROUND TEST GRID**

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Contract W912DY-04-D-0011, TO 004  
March 2006



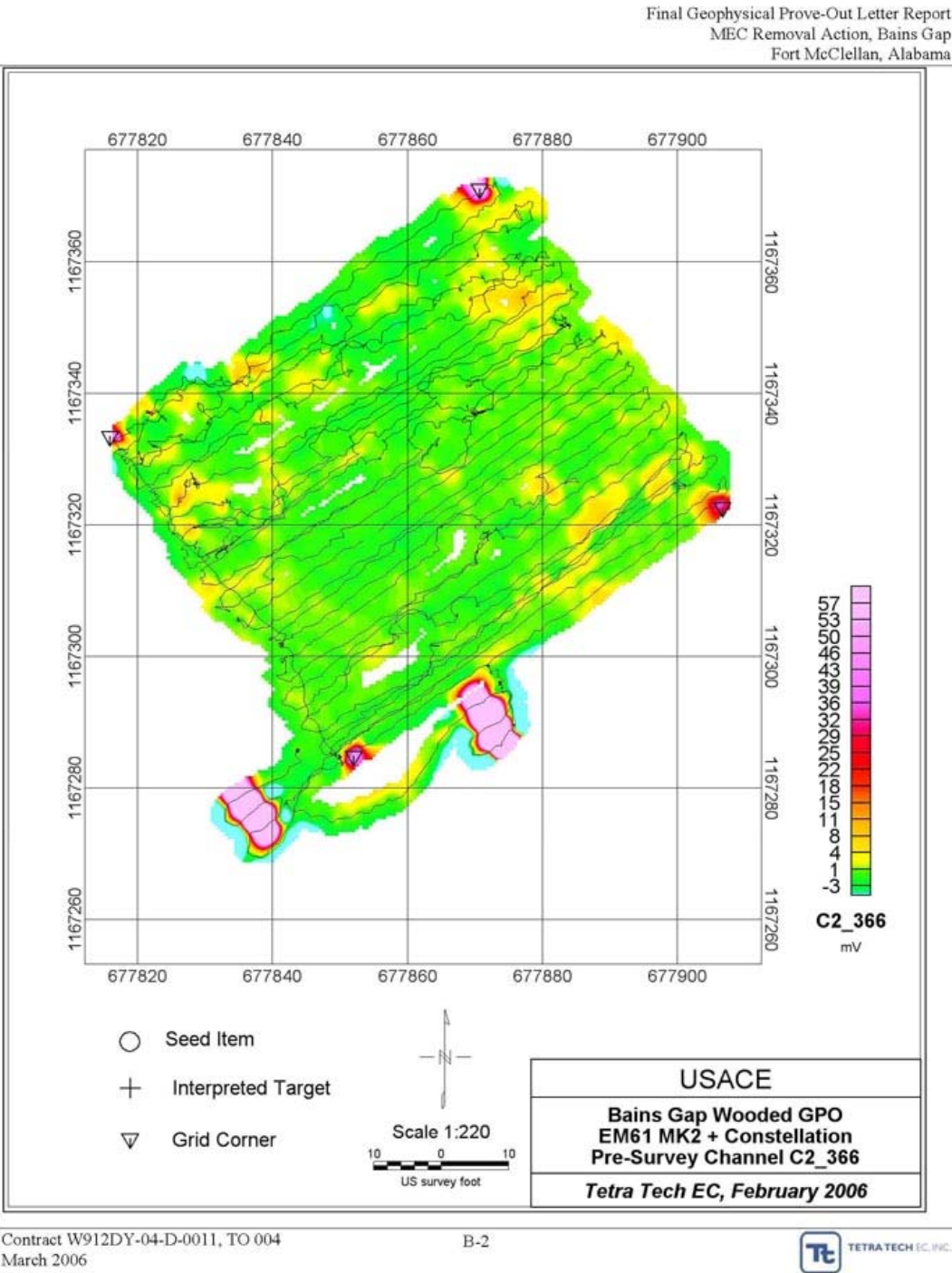
Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama



Contract W912DY-04-D-0011, TO 004  
March 2006

B-1





Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama

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## APPENDIX C

### TABLES

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Contract W912DY-04-D-0011, TO 004  
March 2006





Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama

**TABLE 1 SEED ITEMS OPEN TEST GRID**

X	Y	TARGET ID	ITEM	DEPTH(IN)	ORIENTATION
677699.94	1167164.58	a1	37mm	4.00	Horizontal
677708.37	1167173.14	a2	37mm	4.00	Vertical
677719.73	1167188.12	a3	81mm	34.00	Horizontal
677721.10	1167175.99	a4	2.36" rocket	26.00	Horizontal
677730.10	1167179.32	a5	rocket motor	12.00	Horizontal
677723.37	1167167.69	a6	37mm	16.00	Horizontal
677735.00	1167169.03	a7	60mm	12.00	Vertical
677735.62	1167156.66	a8	MKII HG	8.00	Vertical
677745.30	1167155.03	a9	2.36" rocket	6.00	Vertical
677743.41	1167136.92	a10	Anti Tank Mine	6.00	Horizontal
677726.67	1167132.67	a11	60mm	6.00	Vertical
677718.25	1167118.37	a12	MKII HG	4.00	Horizontal
677719.58	1167146.36	a13	37mm	0.00	Horizontal
677688.23	1167097.99	a14	3 "stokes	20.00	Horizontal
677704.27	1167108.58	a15	3 "stokes	32.00	Horizontal
677694.61	1167113.24	a16	75mm	30.00	Horizontal
677709.18	1167133.61	a17	60mm	25.00	45 degrees
677691.87	1167128.25	a18	75mm	12.00	Vertical
677681.35	1167118.85	a19	MKII HG	14.00	Horizontal
677673.49	1167132.86	a20	75mm	18.00	45 degrees
677666.45	1167141.88	a21	37mm	4.00	45 degrees
677680.90	1167152.03	a22	slap flare	4.00	45 degrees
677706.20	1167151.98	a23	105mm	45.00	45 degrees
677753.84	1167216.57	a24	37mm	4.00	Horizontal
677765.13	1167208.06	a25	37mm	4.00	Vertical
677771.70	1167196.19	a26	81mm	17.00	Horizontal
677771.95	1167190.79	a27	2.36" rocket	26.00	Horizontal
677781.41	1167187.60	a28	rocket motor	12.00	Horizontal
677794.28	1167178.14	a29	37mm	16.00	Horizontal
677775.16	1167162.11	a30	60mm	12.00	Vertical
677767.82	1167173.71	a31	MKII HG	8.00	Vertical
677763.33	1167167.94	a32	2.36" rocket	6.00	Vertical
677750.42	1167179.97	a33	60mm	6.00	Horizontal
677756.51	1167195.77	a34	60mm	6.00	Vertical
677740.94	1167197.48	a35	MKII HG	4.00	Horizontal
677741.04	1167180.67	a36	37mm	0.00	Horizontal
677728.58	1167178.52	a37	3 "stokes	20.00	Horizontal
677733.40	1167171.79	a38	3 "stokes	32.00	Horizontal
677743.27	1167161.79	a39	75mm	30.00	Horizontal
677758.76	1167148.27	a40	81mm	25.00	45 degrees

Contract W912DY-04-D-0011, TO 004  
March 2006

C-1





Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama

TABLE 1 SEED ITEMS OPEN TEST GRID					
X	Y	TARGET ID	ITEM	DEPTH(IN)	ORIENTATION
677697.46	1167163.21	a41	75mm	12.00	Vertical
677699.23	1167155.70	a42	MKII HG	0.00	Horizontal
677700.11	1167144.91	a43	75mm	18.00	45 degrees
677715.77	1167137.08	a44	37mm	4.00	45 degrees
677715.85	1167112.69	a45	slap flare	4.00	Vertical
677706.94	1167104.36	a46	105mm	10.00	Vertical
677693.62	1167134.69	a47	81mm	34.00	Vertical
677683.47	1167133.54	a48	rocket motor	12.00	Vertical
677680.56	1167145.54	a49	3 "stokes	20.00	Vertical
677674.37	1167119.69	a50	37mm	2.00	Horizontal
677753.19	1167226.71	NE	corner point		
677651.45	1167138.05	NW	corner point		
677762.26	1167147.30	M1	mid point		
677728.18	1167117.92	M2	mid point		
677685.25	1167167.49	M3	mid point		
677719.52	1167196.53	M4	mid point		

SEED ITEMS WOODED TEST GRID

Surveyed	Surveyed	Target	Item	Measured	Orientation
Easting (ft)	Northing (ft)	ID	Description	Depth(In)	
677856.4	1167299	1	18" rebar	0	Horizontal
677852.3	1167317	2	6x6 plate	0	Horizontal
677833.1	1167325	3	12" wire	0	Horizontal
677829.6	1167337	4	3x3metal plate	0	Horizontal
677846.3	1167331	5	(3) 8" wires	0	Horizontal
677839.3	1167347	6	3x3 metal plate	0	Horizontal
677861.6	1167342	7	4x4 scrap metal	0	Horizontal
677866.7	1167353	8	4x2 scrap metal	0	Horizontal
677885.9	1167336	9	3x2 srapp metal	0	Horizontal
677874.9	1167318	10	3x2 scrap metal	0	Horizontal
677851.8	1167344	11	5x5 scrap metal	0	Horizontal

Contract W912DY-04-D-0011, TO 004  
March 2006

C-2



Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama

**TABLE 2**  
**CORNER POINTS TEST GRID 1 (ft)**

CORNER POINT	X	Y
SW	677693.96	1167088.76
SE	677796.54	1167176.86
NE	677753.19	1167226.71
NW	677651.45	1167138.05
M1	677762.26	1167147.30
M2	677728.18	1167117.92
M3	677685.25	1167167.49
M4	677719.52	1167196.53

**Test Grid 2 (ft)**

Corner Point	X ft	Y ft
SW	677825.1	1167325.0
SE	677868.1	1167300.0
NE	677911.9	1167375.0
NW	677869.0	1167401.0

Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama

TABLE 3 RTS OPEN GRID RESULTS

Open Target	Surveyed Easting (ft)	Surveyed Northing (ft)	Measured Depth (ft)	Item Description	Orientation	Interrelated Easting (ft)	Interrelated Northing (ft)	Interrelated Position Error (ft)	Bottom C2 216 mV	Bottom C2 388 mV	Bottom C2 660 mV	Too Coil C1 660 mV	Estimated Depth Inches
a1	677699.94	1167164.58	4	37mm	Horizontal	677697.59	1167164.26	2.37	27	17.2	8.3	9.3	15.5
a2	677708.37	1167173.14	4	37mm	Vertical	677708.22	1167173.56	0.45	30.3	21	10.4	11.8	15.7
a3	677719.73	1167188.12	34	81mm	Horizontal	677718.96	1167187.69	0.88	8.9	6.5	2.8	4.2	42.6
a4	677721.10	1167175.99	26	2.36 rocket	Horizontal	677719.49	1167174.78	2.01	6.1	3.9	1.6	2.8	75.5
a5	677730.10	1167179.32	12	rocket motor	Horizontal	677729.10	1167179.06	1.03	61.9	42.1	22.8	24.8	12.9
a6	677723.37	1167167.69	16	37mm	Horizontal	677723.42	1167167.27	0.45	8.3	5.4	1.8	2.2	22.8
a7	677735.00	1167169.03	12	60mm	Vertical	677734.95	1167168.58	0.45	75	53.4	29.5	33.2	15.5
a8	677735.62	1167156.66	8	MKII HG	Vertical	677735.56	1167156.79	0.14	26.8	16.4	6.1	6.3	8.9
a9	677745.30	1167155.03	6	2.36 rocket	Vertical	677746.05	1167155.56	0.92	161.5	119.5	77.5	84	12.4
a10	677743.41	1167136.92	6	Anti Tank Mine	Horizontal	677743.16	1167137.30	0.46	1512.9	1079.5	593	607.5	7.9
a11	677726.67	1167132.67	6	60mm	Vertical	677726.48	1167132.85	0.26	89.3	49.7	27.6	31.6	16.6
a12	677718.25	1167118.37	4	MKII HG	Horizontal	677718.47	1167117.77	0.64	18.7	11.1	4.1	3.5	0
a13	677719.58	1167146.36	0	37mm	Horizontal	677719.49	1167146.21	0.17	43.9	29.2	14	11.8	0
a14	677688.23	1167097.99	20	3 stokes	Horizontal	677688.91	1167098.17	0.70	50.9	32.9	17.4	19.3	14.4
a15	677704.27	1167108.58	32	3 stokes	Horizontal	677703.48	1167107.95	1.01	12.8	8.3	4.3	5.1	19.3
a16	677694.61	1167113.24	30	75mm	Horizontal	677694.42	1167112.93	0.37	13.8	9.1	4.3	6	36.1
a17	677709.18	1167133.61	25	60mm	45 degrees	677708.92	1167135.29	1.70	8.5	5.4	1.8	2.9	47.7
a18	677691.87	1167128.25	12	75mm	Vertical	677692.41	1167128.39	0.55	55.6	40.6	23.8	28.6	20.7
a19	677681.35	1167118.85	14	MKII HG	Horizontal	677681.68	1167119.01	0.37	9.7	5.8	1.9	1.8	0
a20	677673.49	1167132.86	18	75mm	45 degrees	677673.54	1167132.76	0.11	29.6	20.8	10.6	13.8	27.3
a21	677686.45	1167141.88	4	37mm	45 degrees	677686.34	1167141.67	0.24	33.9	22.7	12	11.3	0.9
a22	677680.90	1167152.03	4	slap flare	45 degrees	677680.79	1167152.50	0.49	46.5	28.4	9.3	8.5	0
a23	677706.20	1167151.98	45	105mm	45 degrees	677706.85	1167151.81	0.48	10.5	6.9	3	3.6	22.5
a24	677753.84	1167216.57	4	37mm	Horizontal	677753.12	1167216.98	0.82	28.4	19.2	9.7	8.3	0
a25	677765.13	1167208.06	4	37mm	Vertical	677764.92	1167207.28	0.81	48.7	36.3	24.8	23.5	0.8
a26	677771.70	1167196.19	17	81mm	Horizontal	677771.82	1167195.35	0.85	29.2	18.6	8.8	9.2	9.4

Contract W912DY-04-D-0011, TO 004  
March 2006



C-4



Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama

a27	677771.95	1167190.79	26	2.36 rocket	Horizontal	677772.05	1167189.35	1.45	11.4	7.5	2.8	2.7	3.9
a28	677781.41	1167187.60	12	rocket motor	Horizontal	677780.90	1167187.01	0.78	12.3	8.5	4.4	5.2	19.2
a29	677794.28	1167178.14	16	37mm	Horizontal	677793.31	1167178.28	0.98	23.7	17.4	12	13.1	12.9
a30	677775.16	1167162.11	12	60mm	Vertical	677774.99	1167161.28	0.85	22	15.2	7.7	9.2	20
a31	677767.82	1167173.71	8	MKII HG	Vertical	677767.31	1167173.43	0.58	30.5	19.7	7.5	8.1	11.9
a32	677763.33	1167167.94	6	2.36 rocket	Vertical	677762.73	1167167.44	0.78	98.1	74.1	47.8	55.6	18
a33	677750.42	1167179.97	6	60mm	Horizontal	677750.33	1167179.41	0.57	56.8	38.8	19.7	17.9	0
a34	677756.51	1167195.77	6	60mm	Vertical	677755.82	1167195.90	0.90	83.2	62.8	31.4	34.4	13.1
a35	677740.94	1167197.48	4	MKII HG	Horizontal	677740.37	1167197.50	0.57	12.9	8.3	2.6	2.9	16.2
a36	677741.04	1167180.67	0	37mm	Horizontal	677740.89	1167180.37	0.33	48.7	30.8	15.3	12.8	0
a37	677728.58	1167178.52	20	3 stokes	Horizontal	677729.10	1167179.06	0.75	80.6	53.3	28	29	8.7
a38	677733.40	1167171.79	32	3 stokes	Horizontal	677732.85	1167171.20	0.80	21.6	14.5	6.5	9.8	43.7
a39	677743.27	1167161.79	30	75mm	Horizontal	677742.99	1167161.59	0.35	9	5.9	2.5	3.6	37.6
a40	677758.76	1167148.27	25	81mm	45 degrees	677758.36	1167148.22	0.40	29.3	20.5	12	15.5	26.7
a41	677697.46	1167163.21	12	75mm	Vertical	677697.59	1167164.26	1.06	44.7	31.9	18.6	22.6	21.5
a42	677699.23	1167155.70	0	MKII HG	Horizontal	677698.86	1167155.65	0.57	24.8	15.2	6.1	5.7	0
a43	677700.11	1167144.91	18	75mm	45 degrees	677699.66	1167144.47	0.63	30.2	20	10.9	13.3	22.2
a44	677715.77	1167137.08	4	37mm	45 degrees	677715.07	1167136.57	0.87	22.5	14.8	7.8	7.7	4.8
a45	677715.85	1167112.69	4	slap flare	Vertical	677714.72	1167112.67	1.13	7.1	4.8	2.1	3.9	89.8
a46	677706.94	1167104.36	?	105mm	Vertical	677706.38	1167104.19	0.58	20.9	15.1	8.5	11.4	30.3
a47	677693.62	1167134.69	34	81mm	Vertical	677692.93	1167135.12	0.81	203.7	154.3	87.9	98.6	15.1
a48	677683.47	1167133.54	12	rocket motor	Vertical	677683.23	1167133.55	0.24	52.2	40.1	23.5	31.6	30.7
a49	677680.56	1167145.54	20	3 stokes	Vertical	677679.54	1167145.64	1.03	27.4	15.3	4.4	4.3	3.1
a50	677674.37	1167119.69	2	37mm	Horizontal	677674.23	1167119.31	0.41	48.5	33.9	18.6	16	0
								max. error					2.37
								min error					0.11
								avg error					0.72

Contract W912DY-04-D-0011, TO 004  
March 2006

C-5



Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama

Wooded GPO		Measured				Orientation		Interpreted		Interpreted		Interpreted	
Target	ID	Surveyed Easting (ft)	Surveyed Northing (ft)	Measured Depth(ft)	Item Description			Easting (ft)	Northing (ft)	Easting (ft)	Northing (ft)	Position Error (ft)	
1	1	677856.373	1167299.054	0	18" rebar	Horizontal		677857.38	1167299.212			1.01	
2	2	677852.327	1167316.762	0	6x6 plate	Horizontal		677852.64	1167317			0.39	
3	3	677833.077	1167325.107	0	12" wire	Horizontal		677833.07	1167325.182			0.08	
4	4	677829.618	1167337.205	0	3x3 metal plate	Horizontal		677829.87	1167337.633			0.50	
5	5	677846.299	1167330.891	0	(3) 8" wires	Horizontal		677847.29	1167331.174			1.03	
6	6	677839.297	1167347.06	0	3x3 metal plate	Horizontal		677838.94	1167347.594			0.64	
7	7	677861.585	1167342.103	0	4x4 scrap metal	Horizontal		677861.53	1167342.436			0.34	
8	8	677866.73	1167353.4	0	4x2 scrap metal	Horizontal		677866.87	1167353.82			0.44	
9	9	677885.853	1167335.748	0	3x2 scrap metal	Horizontal		677885.72	1167336.388			0.65	
10	10	677874.854	1167317.79	0	3x2 scrap metal	Horizontal		677874.16	1167317.533			0.74	
11	11	677851.751	1167344.482	0	5x5 scrap metal	Horizontal		677851.22	1167343.859			0.82	
													max. error
													min error
													avg error
													1.03
													0.08
													0.60

Contract W912DY-04-D-0011, TO 004  
March 2006

C-6



Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama

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**APPENDIX D**  
**STATIC TEST**

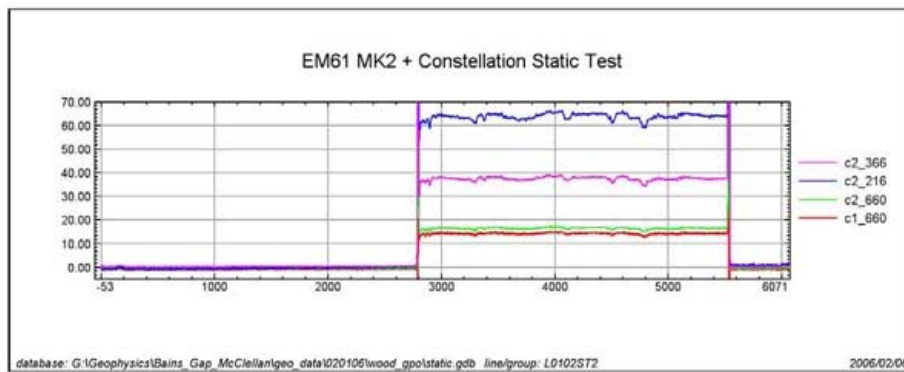
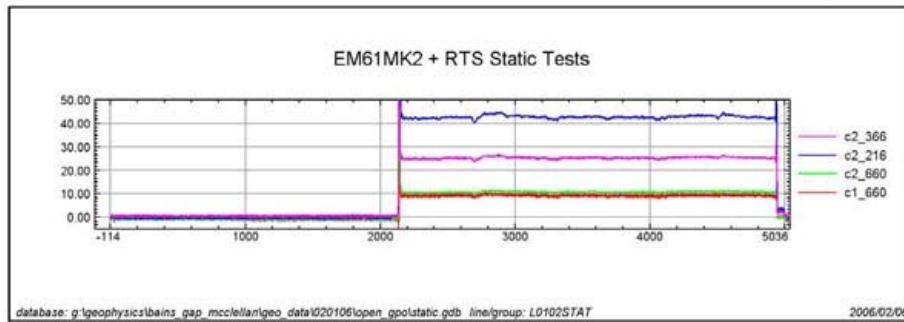
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Contract W912DY-04-D-0011, TO 004  
March 2006





Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama



Contract W912DY-04-D-0011, TO 004  
March 2006

D-1



Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama

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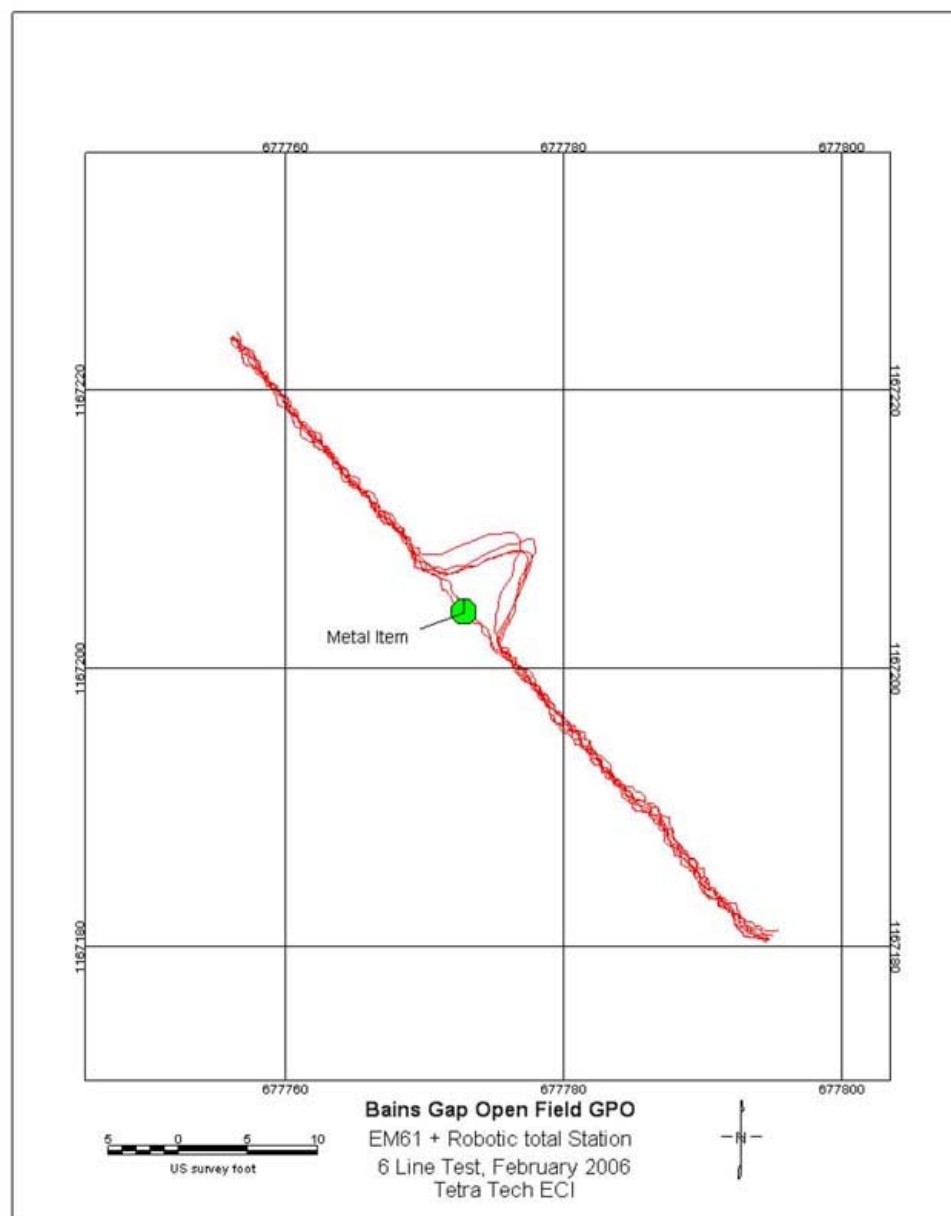
**APPENDIX E  
SIX LINE TEST**

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Contract W912DY-04-D-0011, TO 004  
March 2006



Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama

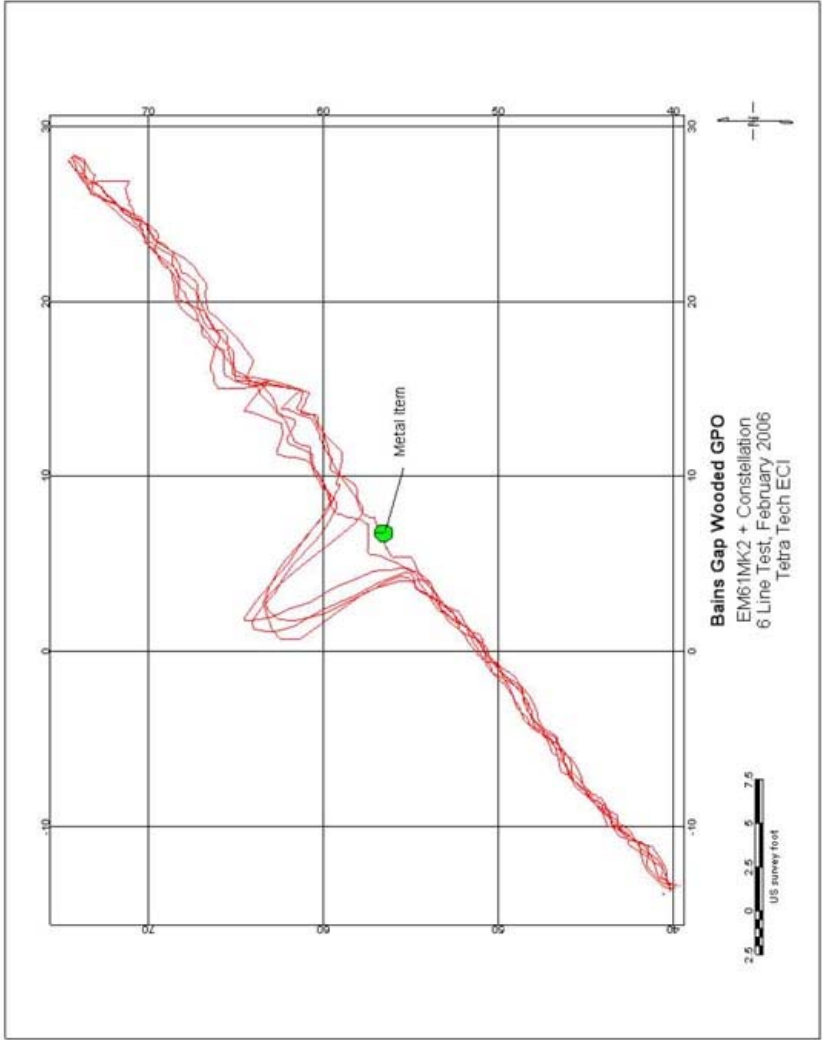


Contract W912DY-04-D-0011, TO 004  
March 2006

E-1



Final Geophysical Prove-Out Letter Report  
 MEC Removal Action, Bains Gap  
 Fort McClellan, Alabama



Contract W912DY-04-D-0011, TO 004  
 March 2006

E-2

Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama

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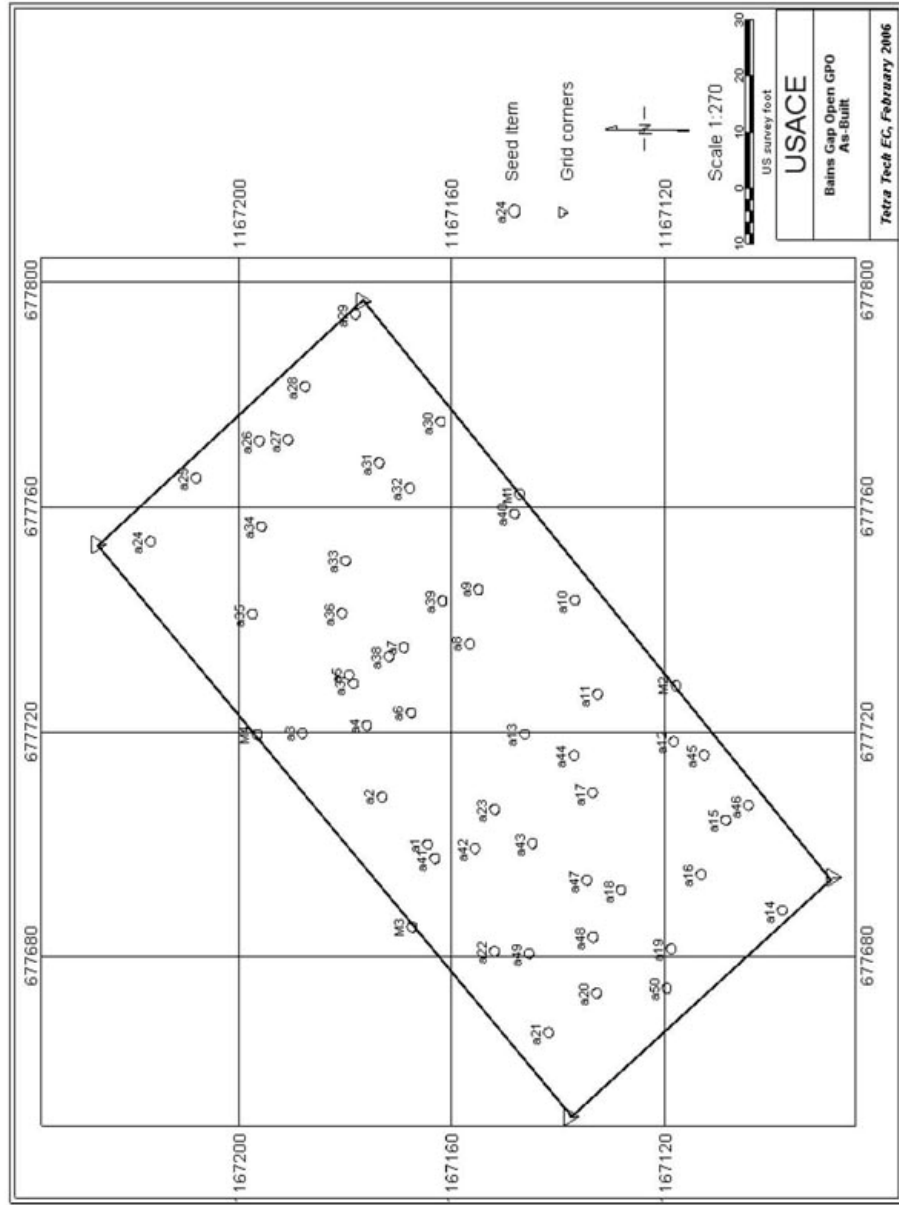
**APPENDIX F**  
**OPEN AND WOODED TEST GRID AS-BUILT DRAWINGS**

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Contract W912DY-04-D-0011, TO 004  
March 2006



Final Geophysical Prove-Out Letter Report  
 MEC Removal Action, Bains Gap  
 Fort McClellan, Alabama

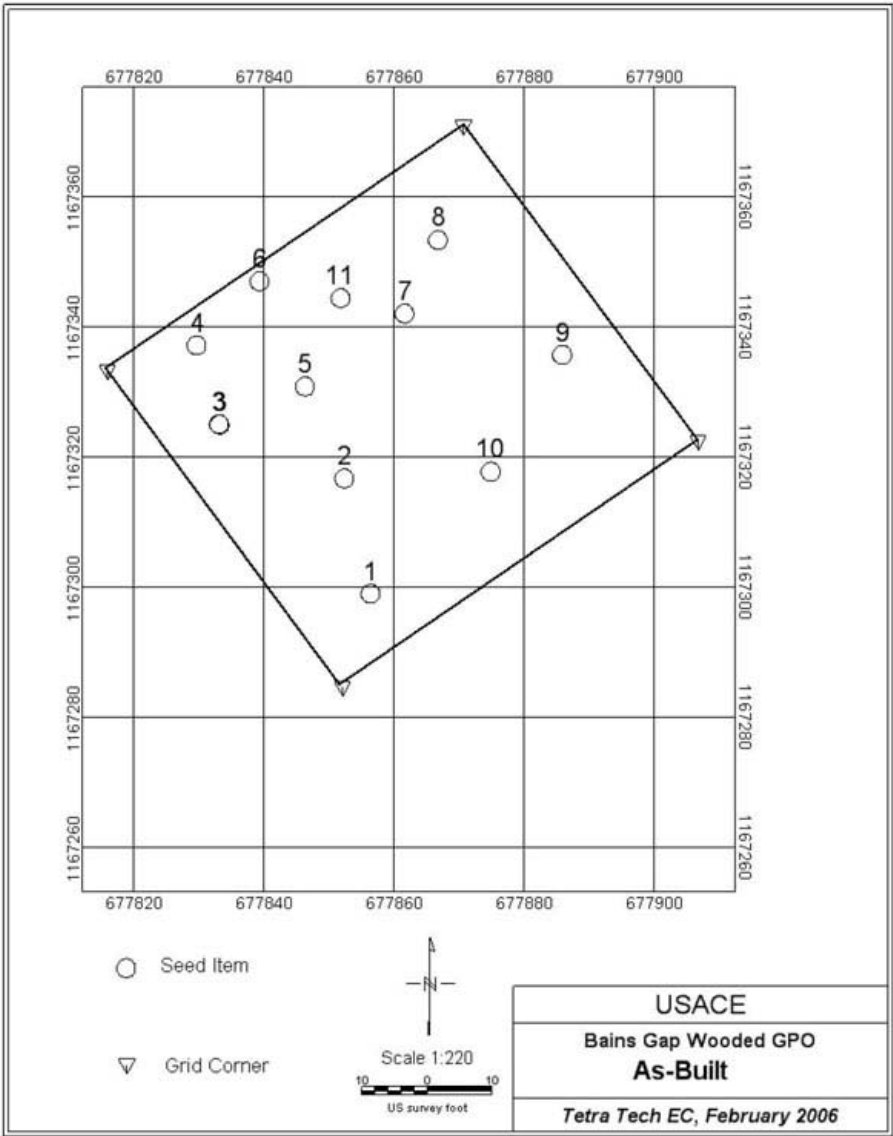


F-1

Contract W912DY-04-D-0011, TO 004  
 March 2006



Final Geophysical Prove-Out Letter Report  
 MEC Removal Action, Bains Gap  
 Fort McClellan, Alabama



Contract W912DY-04-D-0011, TO 004  
 March 2006

F-2



Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama

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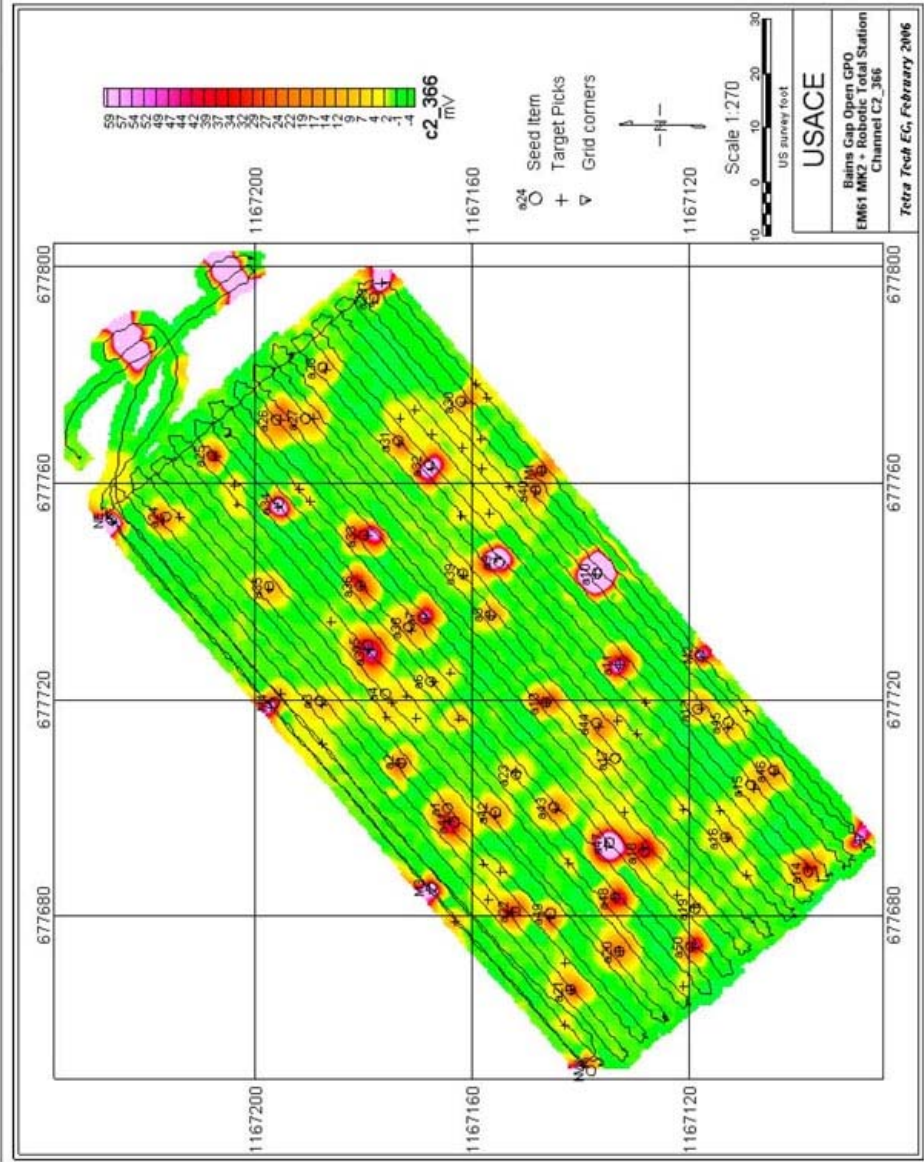
**APPENDIX G**  
**RTS AND CONSTELLATION GRID MAPS**

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Contract W912DY-04-D-0011, TO 004  
March 2006



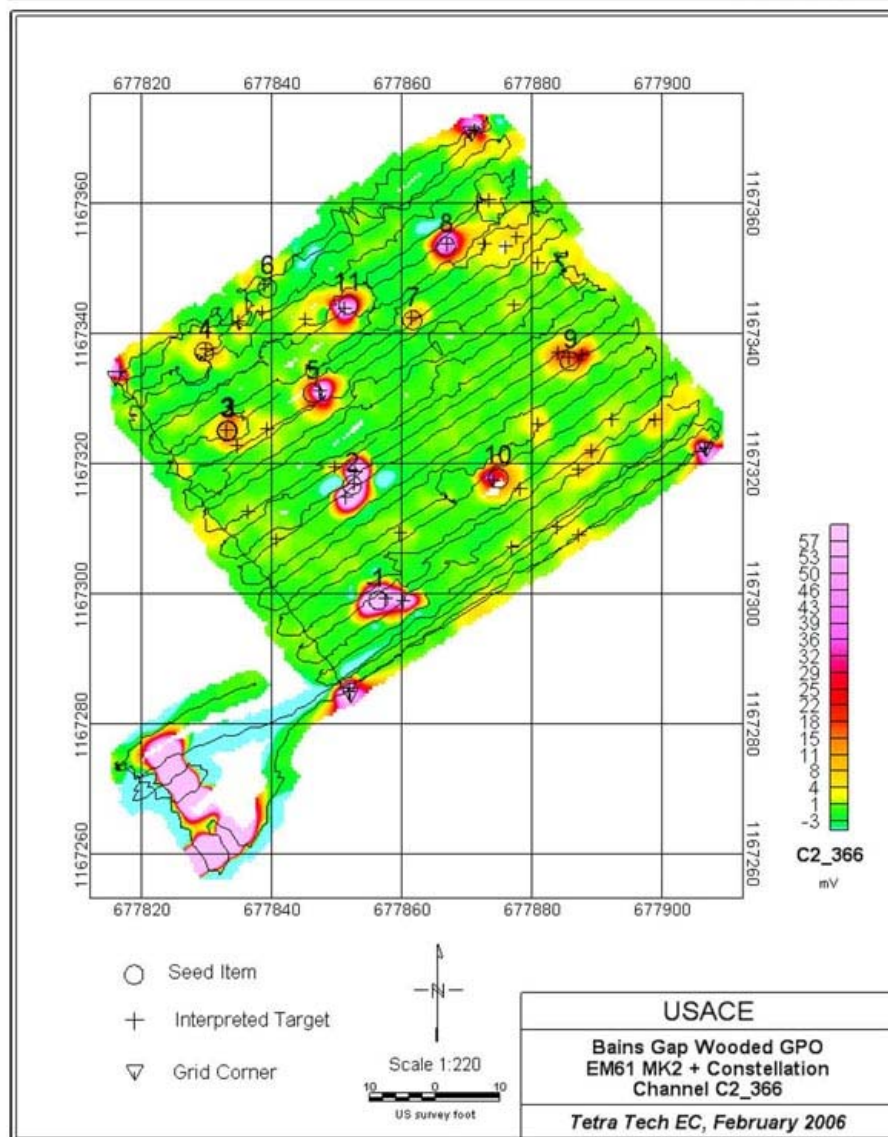
Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama



Contract W912DY-04-D-0011, TO 004  
March 2006

G-1

Final Geophysical Prove-Out Letter Report  
MEC Removal Action, Bains Gap  
Fort McClellan, Alabama

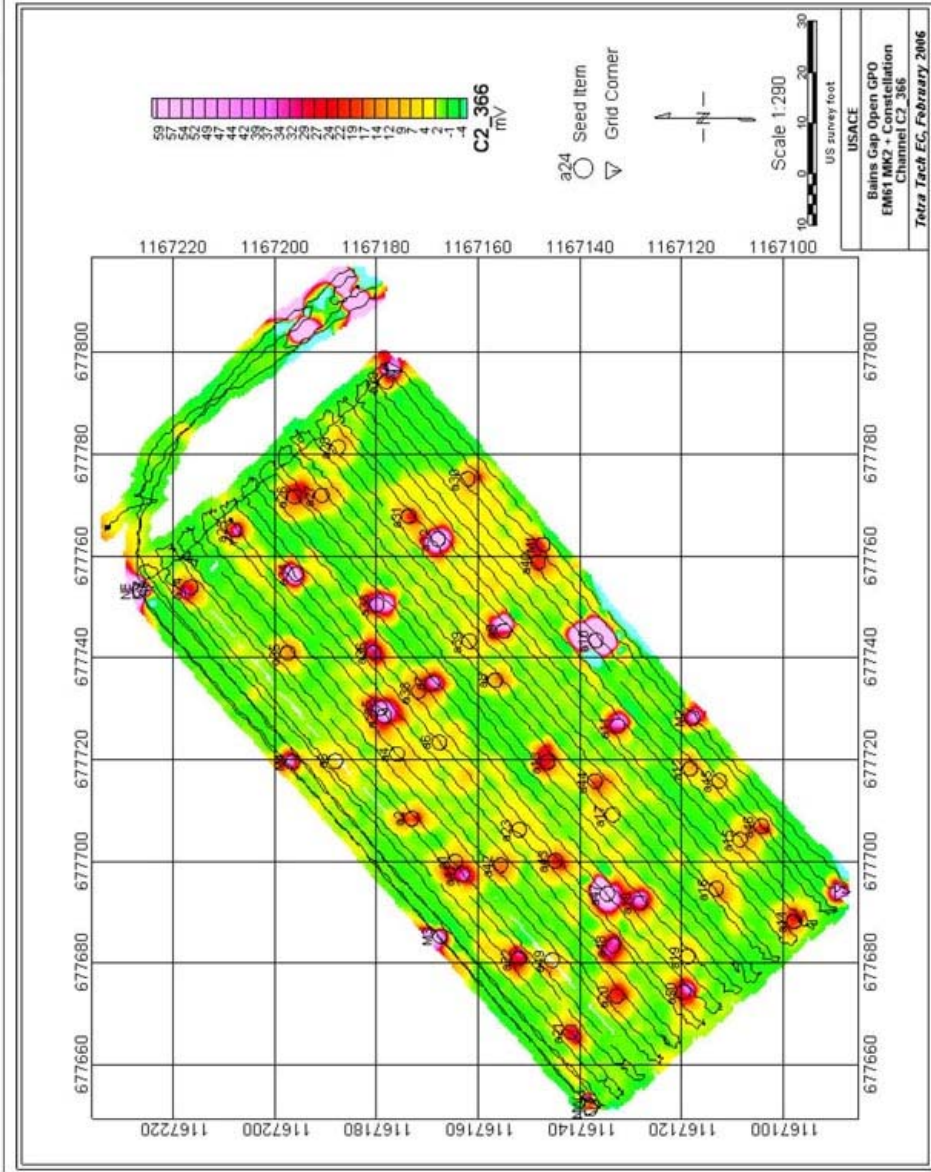


Contract W912DY-04-D-0011, TO 004  
March 2006

G-2



Final Geophysical Prove-Out Letter Report  
 MEC Removal Action, Bains Gap  
 Fort McClellan, Alabama



Contract W912DY-04-D-0011, TO 004  
 March 2006

G-3



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